

Abrupt Convergence and Escape Behavior for Birth and Death Chains

J. Barrera · O. Bertoncini · R. Fernández

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Abstract We link two phenomena concerning the asymptotical behavior of stochastic processes: (i) abrupt convergence or cut-off phenomenon, and (ii) the escape behavior usually associated to exit from metastability. The former is characterized by convergence at asymptotically deterministic times, while the convergence times for the latter are exponentially distributed. We compare and study both phenomena for discrete-time birth-and-death chains on \mathbb{Z} with drift towards zero. In particular, this includes energy-driven evolutions with energy functions in the form of a single well. Under suitable drift hypotheses, we show that there is both an abrupt convergence towards zero and escape behavior in the other direction. Furthermore, as the evolutions are reversible, the law of the final escape trajectory coincides with the time reverse of the law of cut-off paths. Thus, for evolutions defined by

J. Barrera (✉)
Facultad de Ingeniería y Ciencias, Universidad Adolfo Ibáñez, Avda. Diagonal Las Torres 2640,
Peñalolén, Santiago, Chile
e-mail: javiera.barrera@uai.cl

O. Bertoncini · R. Fernández
Laboratoire de Mathématiques Raphaël Salem, UMR 6085 CNRS-Université de Rouen, Avenue
de l'Université, BP.12, Technopôle du Madrillet, 76801 Saint-Étienne-du-Rouvray, France

O. Bertoncini
e-mail: olivier.bertoncini@univ-rouen.fr

R. Fernández
e-mail: roberto.fernandez@univ-rouen.fr

Present address:

O. Bertoncini
Departamento de Física, Universidade de Aveiro, Campus Universitário de Santiago, 3810-193 Aveiro,
Portugal
e-mail: olivier@ua.pt

Present address:

R. Fernández
Department of Mathematics, Utrecht University, P.O. Box 80010, 3508 TA Utrecht, The Netherlands
e-mail: r.fernandez1@uu.nl

one-dimensional energy wells with sufficiently steep walls, cut-off and escape behavior are related by time inversion.

Keywords Cut-off · Metastability · Hitting time · Exit-times · Reversibility

1 Introduction

The *cut-off* phenomenon, first identified and formalized in the early eighties [2, 3], is by now a well studied feature of Markov processes (see [25, 26, 47, 48] for reviews). The phenomenon refers to an asymptotically drastic convergence of a family of stochastic processes $X^{(a)}$ labeled by some parameter a . As $a \rightarrow \infty$, a suitable distance between the laws $\mathbb{P}(X^{(a)}(t) \in \bullet)$ and the corresponding invariant measures $\pi^{(a)}(\bullet)$ converges, in macroscopic time units, to a step function centered at *deterministic* times t_a^{cut} . More precisely, the function $a \rightarrow t_a^{\text{cut}}$ is such that the distance is asymptotically maximal for times smaller than $t_a^{\text{cut}} - o(t_a^{\text{cut}})$ and asymptotically zero for times larger than $t_a^{\text{cut}} + o(t_a^{\text{cut}})$ (Fig. 1). The term *cut-off* is naturally associated to such an “all/nothing” or “1/0” behavior, but it has the drawback of being used with other meanings in statistical mechanics and theoretical physics. Alternative names have been proposed, including *threshold phenomenon* [3] and *abrupt convergence* [55]. It has also been called *abrupt switch* in a precursor work [1] based on mixing times rather than distances between measures.

Despite growing interest among probabilists, cut-off convergence has been largely ignored within mathematical statistical mechanics ([38] is the only exception we know of, besides our previous announcement [9] and the thesis of one of us [8]). As a tentative justification of this situation, we stress the fact that cut-off studies have often been performed in a relatively elaborated setting that involves a certain amount of technical complexity. Indeed, cut-off was initially studied in evolutions defined by group actions (e.g. card shuffling) [2, 3]. Emphasis was, therefore, put into Fourier techniques [25]. Subsequently [3, 5, 23, 27, 28, 30], the phenomenon was associated to the existence of “strong uniform (coupling) times” and to symmetry and multiplicity properties of second eigenvalues of transition matrices, see [26] for a review. It has also been associated to exponential speed of convergence in [4, 52] and [36]. This fostered the use of notions and techniques issued from diverse mathematical fields, ranging from combinatorics to functional analysis, see [47, 48]. The mathematical richness of these studies may have prevented potential audiences from fully appreciating the probabilistic meaning of the phenomenon.

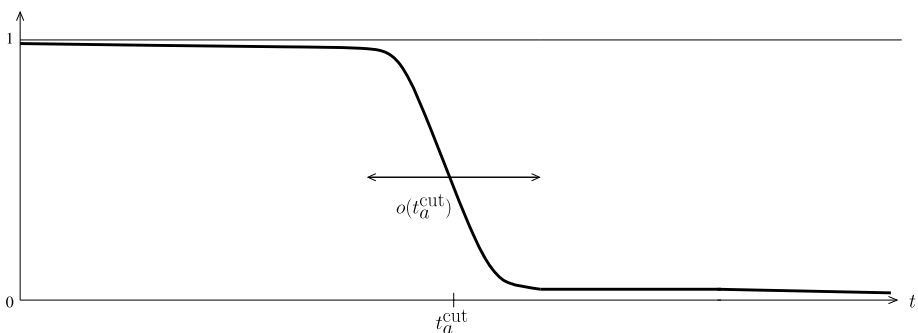
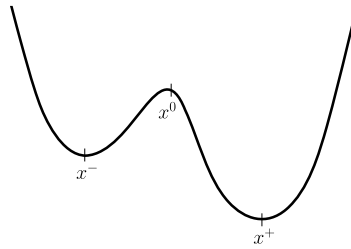


Fig. 1 Distance to equilibrium during abrupt convergence

Fig. 2 The local minimum at x^- leads to metastability



In all these references, the existence of the phenomenon is proven through a precise estimation of the sequence t_a^{cut} of cut-off times. This precision comes at a high technical price and is largely responsible for the variety of treatments found in the literature. It is clear that the theory would benefit from the disentanglement of the proof of the *existence* of a cut-off from the more delicate determination of the actual cut-off times. A contribution in this direction is the work done in relation with the conjecture formulated by Y. Peres in 2004. The conjecture states that in different natural settings a necessary and sufficient condition for a process to have cut-off is that the product of mixing time and the spectral-gap tends to infinity. It was proved that the conjecture is true for Markov chains for the L^p norm with $p > 1$ in [22]. It was also proved to be true for birth and death chains in separation distance in [29] and in total variation distance in [31]. These articles have been a big contribution to the understanding of the phenomenon, yet the condition to observe the phenomenon still relies in the spectral structure of the chain and the behavior of the distance. In our opinion, this work should be complemented by an approach based on the analysis of typical trajectories, which would reveal, more clearly, the underlying probabilistic mechanism leading to cut-off among all possible patterns of convergence. The present work points in this direction.

An alternative, more probabilistic approach proposed in the last decade [40, 52–54] offers some advantages regarding the above criticism. In this approach, cut-off is associated to the existence of an appropriate drift in stochastic processes or sampling schemes, and arguments are based on the behavior of hitting times [4, 36, 37]. Furthermore, the approach includes some general criteria for the existence of cut-off as illustrated by Proposition 1 below (taken from [40]). The resulting description offered some tantalizing contrast with another, quite different type of convergence associated to metastability. This observation triggered our research.

From a physical point of view, a system exhibits metastability if it stays trapped for exceptionally long times in a state different from true equilibrium (e.g. supercooled water). The final transition to equilibrium is rather sudden and happens at “unpredictable” times. Mathematically, it is the behavior expected for evolutions designed to find a minima x^+ of some energy function $H(x)$, when the system is “captured” by a local minimum at x^- (Fig. 2).

Unlike cut-off, metastable behavior has been thoroughly studied within rigorous statistical mechanics. The basic scenario was described in a seminal paper [21] that is contemporary of the first cut-off papers: A system driven downhill towards x^- will stay for a long time around this point until suddenly, at some random instant t^{esc} , an escape trajectory unfolds, that takes it over the barrier at x^0 and down to the true minimum x^+ . The law of t^{esc} converges to an exponential as the “barrier height” $x^0 - x^-$ grows in a suitable manner. In a typical trajectory, the distance to x^+ follows curves similar to those of Fig. 1, except that the jump-times t_a are exponentially distributed rather than determinist. The parameter a diverges with the height and/or steepness of the small well.

This picture, borrowed from the theory of randomly perturbed dynamical systems [33], has been called “path approach to metastability”. It has subsequently been refined and systematized [43, 44, 51]; see [39, 45, 46] for overviews. Escape from metastability happens through a very narrow choice of trajectories, known as the *exit tube*, which has been determined in a very precise manner for a number of spin dynamics [34, 35, 41, 42, 49, 50]. A more recent and efficient alternative rigorous treatment of metastability is based on potential theory [7, 15–20]. The approach relies on an optimization principle which allows the determination of metastable behavior through suitable trial functions, without an in-depth study of trajectories (see [12–14] for reviews).

Cut-off and escape behavior show, therefore, both similar and contrasting features. On the one hand, both are *asymptotic* phenomena: they show up when a suitable parameter is sufficiently large and their very definitions rely on limit properties. On the other hand, while both convergences are sudden, the laws of the convergence times are antipodal: deterministic for cut-off and exponential (randomness without memory) for escapes. There are also differences in focus: cut-off studies emphasize distance between measures, while exit times are the object of metastability studies. In this paper we present a setting where, in fact, these phenomena are intertwined.

We adopt a relatively simple, but sufficiently rich, framework where both the probabilistic approach to cut-off of [40, 52–54] and the path approach to metastability of [33] can be applied. We consider birth-and-death chains with a drift (towards the origin) and focus on hitting times for excursions along and against the drift. Under reasonable hypothesis on the drift, we show that cut-off behavior characterizes the first type of excursions, where the latter requires exponential escape times. If an energy function is associated to the drift, this results can be interpreted as saying that, if the well is sufficiently steep or high (and its walls are sufficiently smooth), climbing along a wall requires an exponential time while descents are abrupt. Furthermore, by reversibility, both types of excursions are related by time inversion: the law of escape trajectories equals the time reverse of the law of cut-off paths. In particular, our results apply to rather general recurrent random walks and to the Ehrenfest model. The latter is a kind of border line case, as it is associated to a well whose walls are not as steep as required in standard metastability studies.

Our results explain, in part, why cut-off phenomena has been largely ignored by physics-minded researchers. In settings such as ours—which includes, for instance, examples in [21]—it corresponds to the “trivial” downhill evolution of a system falling in an energy well. In these cases, our work suggests a more detailed decomposition of metastable evolutions. Coming back to Fig. 2, the escape from the local minimum at x^- to the absolute one at x^+ can be decomposed in three stage: (i) the exit from x^- to the left-vicinity of x^0 , (ii) the transition to the right of x^0 , and (iii) the descent to x^+ . The exponential time typical of the transitions to equilibrium—from x^- to x^+ —is, in fact, determined by stage (i). The time scale of the other two stages is so much smaller that it disappears under the usual time rescaling. Evolutions in more complicated energy landscapes can, in principle, be decomposed into a sequence of exponentially distributed uphill pieces followed by cut-off-like downhill excursions. Only the uphill stages survive the usual time rescaling, and the resulting theory should merge with existing metastability studies [43, 44, 51].

Furthermore, the equality, modulo time-reversal, of the laws of up- and downhill trajectories clarifies the escape scenario: The final excursion taking the system from the bottom to the top of a well is the reversed of the cut-off trajectory that would take it in the opposite direction. Hence, this upwards motion is done in one stroke, almost without midway hesitations, in an asymptotically deterministic manner. The exponential law of the exit time is due to the fact that the system spends an exponential time around the bottom of the well till the atypical uphill excursion takes place.

As a final disclaimer, let us point out that the intertwining between cut-off and exponential escape times is by no means universal. Exponential escape times are a more robust phenomenon that requires uphill time scales much larger than downhill ones. But the latter need not be cut-off like. Wells whose walls are rugged, or not strictly monotone, yield examples where the downhill time is not abrupt while the uphill law remains exponential. In this sense, knowing that downhill excursions exhibit cut-off conveys more detailed information than knowing that the opposite evolution is escape-like. Nevertheless, our results suggest a profitable association between the cut-off and metastability research communities. It is reasonable to expect that methods devised to study one of the phenomena might be adaptable to the study of the other. This can be of particular interest, for instance to study evolutions involving bidimensional—or multidimensional—wells.

2 Definitions and Results

2.1 The Two Types of Behavior

Cut-off and escape behavior, will be studied at the level of hitting times. Both types of behavior are asymptotic, in the sense that they are characterized by what happens when a certain parameter a diverges. Let us start with the relevant definitions.

Definition 1

- (i) A family of random variables $U^{(a)}$ exhibits cut-off behavior at mean times if

$$\frac{U^{(a)}}{\mathbb{E}[U^{(a)}]} \xrightarrow[a \rightarrow \infty]{\text{Proba}} 1 \quad (2.1)$$

[equivalently, $\lim_{a \rightarrow \infty} \mathbb{P}(U^{(a)} > c\mathbb{E}[U^{(a)}]) = 1$ for $c < 1$ and 0 for $c > 1$].

- (ii) A family of random variables $V^{(a)}$ exhibits escape-time behavior at mean times if

$$\frac{V^{(a)}}{\mathbb{E}[V^{(a)}]} \xrightarrow[a \rightarrow \infty]{\mathcal{L}} \exp(1). \quad (2.2)$$

The original definition of cut-off [1–3] is in terms of the variational distances of invariant and process measures. We pass to variables because the comparison with escape behavior is possible only at the level of hitting times (the measures asymptotically associated to metastable escapes are often reduced to delta-like measures). The connection between both types of definition—in terms of measure-theoretical distances and of hitting times—has been explored in [40], where the following is concluded:

- (i) If the variable $U^{(a)}$ correspond to an absorption time, both definitions are equivalent.
(ii) For a positive recurrent Markov chain $X_a(t)$ on \mathbb{N} with invariant probability measure π and initial state a , the chain admits a cut-off at time t_a if and only if its associated absorbed chain with invariant measure δ_0 admits a cut-off at the same time.

Moreover, our definition of cut-off behavior is covered by a more general definition introduced in Sect. 2 of [22]. This definition applies to any family of non-increasing functions (here $f_a(t) = \mathbb{P}(U^{(a)} > t)$) where no underlying probability structure is needed.

2.2 The Models

Each of the models considered in the sequel corresponds to a family $\{X^{(a)} : a \in \mathbb{N}\}$ of irreducible discrete birth-and-death chains $X^{(a)} = \{X^{(a)}(t) : t \in \mathbb{N} \cup \{0\}\}$ on intervals $\llbracket b, a \rrbracket := \{b, b + 1, \dots, a\} \subset \mathbb{Z}$. Without loss of generality, we choose $a > 0$ and $b \leq 0$. The right endpoint a is the diverging parameter that will reveal the asymptotic behavior. We shall consider two cases: (i) *half well*: $b = 0$, which corresponds to a well in the form of a wedge with a vertical wall at the origin, and (ii) *full well*: b tends to minus infinity as a grows, at a proportional rate (most parameters involved in the definition of the processes will be a -dependent but, to unclog formulas, we shall only exhibit this dependency selectively). Chains with initial state z will be denoted $X_z^{(a)}$.

Each family of chains is characterized by transition probabilities p_x to the right and q_x to the left: $p_x := p(x, x + 1)$, $b \leq x \leq a - 1$, and $q_x := p(x, x - 1)$, $b + 1 \leq x \leq a$, with $p_x, q_x > 0$. The “waiting probabilities” $r_x := p(x, x)$, $b \leq x \leq a$ may be non-zero, but, for each a the chain is required to be aperiodic, thus there is at least one $r_x > 0$. All other transition probabilities are zero ($p_x + q_x + r_x = 1$). Note that the different p ’s and q ’s may depend on a .

As the chain is positive recurrent and aperiodic for each a , then it admits a unique invariant probability measure $\pi^{(a)}$ which is also reversible and can be explicitly written in terms of the transition probabilities:

$$\pi^{(a)}(x) = \begin{cases} \prod_{i=1}^x \frac{p_{i-1}}{q_i} \pi^{(a)}(0) & x \in \llbracket 1, a \rrbracket, \\ \prod_{i=x}^{-1} \frac{q_{i+1}}{p_i} \pi^{(a)}(0) & x \in \llbracket b, -1 \rrbracket. \end{cases} \tag{2.3}$$

This expression follows readily from the reversibility condition $\pi^{(a)}(x)q_x = \pi^{(a)}(x - 1) \times p_{x-1}$. Note that the values of r_x appear only through the normalization constant $\pi^{(a)}(0)$, and hence they are largely irrelevant for the rest of our discussion.

The measure of the interval $\llbracket k, l \rrbracket$, will be denote by: $\pi^{(a)}(\llbracket k, l \rrbracket) := \sum_{i=k}^l \pi^{(a)}(i)$.

We shall focus on the behavior of hitting times

$$T_{x \rightarrow y}^{(a)} = \min\{t \geq 0 : X_x^{(a)}(t) = y\}. \tag{2.4}$$

More specifically, we shall consider $T_{a \rightarrow 0}^{(a)}, T_{b \rightarrow 0}^{(a)}, T_{0 \rightarrow a}^{(a)}, T_{0 \rightarrow b}^{(a)}$ and $T_{0 \rightarrow \{a,b\}}^{(a)} = \min(T_{0 \rightarrow a}^{(a)}, T_{0 \rightarrow b}^{(a)})$. Notice that according to this definition $T_{x \rightarrow x}^{(a)} = 0$ for all x in $\llbracket b, a \rrbracket$, this choice will simplify computations in Sect. 4.

2.3 The Drift Condition

We impose the following drift condition towards 0. For the sake of precision, we state it exactly as needed in proofs. The ensuing comments relate it with the picture in terms of energy wells. Let us recall that in the following definition, transitions probabilities p_x and q_x may depend on a .

Definition 2 A family $X^{(a)}$ of birth-and-death processes has a *strong drift to the left towards 0* (we note 0^+ -SD) if

- (i) The transition probabilities q_x satisfy

$$\inf_{a \in \mathbb{N}} \inf_{x \in \llbracket 1, a \rrbracket} q_x =: K_q > 0. \tag{2.5}$$

(ii) The constant

$$K_a := \sup_{x \in \llbracket 1, a \rrbracket} q_x \mathbb{E}[T_{x \rightarrow x-1}^{(a)}] \tag{2.6}$$

satisfies

$$\frac{K_a^2}{\mathbb{E}[T_{a \rightarrow 0}^{(a)}]} \xrightarrow{a \rightarrow \infty} 0. \tag{2.7}$$

Likewise, it has a *Strong Drift to the right towards 0* (equivalently 0^- -SD) if

(i)

$$\inf_{a \in \mathbb{N}} \inf_{x \in \llbracket b, -1 \rrbracket} p_x =: K_p > 0. \tag{2.8}$$

(ii)

$$K_b := \sup_{x \in \llbracket b, -1 \rrbracket} p_x \mathbb{E}[T_{x \rightarrow x+1}^{(a)}] \tag{2.9}$$

satisfies

$$\frac{K_b^2}{\mathbb{E}[T_{b \rightarrow 0}^{(a)}]} \xrightarrow{a \rightarrow \infty} 0. \tag{2.10}$$

The family $X^{(a)}$ is said to *satisfy the (bilateral) Strong Drift condition towards 0* (0-SD) if it has both 0^+ -SD and 0^- -SD .

Let us discuss the meaning of the 0-SD condition. All of the expressions given above in terms of hitting times have equivalent forms in terms of the invariant measures $\pi^{(a)}$. The connection is provided by the following well known expressions

$$\mathbb{E}[T_{x \rightarrow x-1}^{(a)}] = \frac{\pi^{(a)}(\llbracket x, a \rrbracket)}{q_x \pi^{(a)}(x)}; \quad \mathbb{E}[T_{x \rightarrow x+1}^{(a)}] = \frac{\pi^{(a)}(\llbracket b, x \rrbracket)}{p_x \pi^{(a)}(x)} \tag{2.11}$$

which, for completeness, are proven in Sect. 4 below. As a consequence,

$$K_a = \sup_{x \in \llbracket 0, a \rrbracket} \frac{\pi^{(a)}(\llbracket x, a \rrbracket)}{\pi^{(a)}(x)}; \quad K_b = \sup_{x \in \llbracket b, -1 \rrbracket} \frac{\pi^{(a)}(\llbracket b, x \rrbracket)}{\pi^{(a)}(x)}. \tag{2.12}$$

These expressions show that K_a and K_b provide an exponential bound for the tail of $\pi^{(a)}$. Indeed, by the leftmost identity in (2.12),

$$\frac{\pi^{(a)}(\llbracket x + 1, a \rrbracket)}{\pi^{(a)}(\llbracket x, a \rrbracket)} = 1 - \frac{\pi^{(a)}(x)}{\pi^{(a)}(\llbracket x, a \rrbracket)} \leq 1 - \frac{1}{K_a}. \tag{2.13}$$

Hence, upon iteration,

$$\pi^{(a)}(x) \leq \pi^{(a)}(\llbracket x, a \rrbracket) \leq e^{-\alpha_a x} \quad \text{with } \alpha_a = -\log(1 - 1/K_a), \tag{2.14}$$

for $0 \leq x \leq a$. The rightmost identity in (2.12) yields the same inequalities for $b \leq x \leq 0$, with b in place of a .

The 0-SD condition can be transcribed in terms of energy profiles by proposing a function $H(x)$ such that $p(x, y) \propto \exp\{-[H(x) - H(y)]\}$. Then, $H(x) - H(x - 1) =$

$-(1/2) \log(p_{x-1}/q_x)$ and, by (2.3), $\pi^{(a)}(x)/\pi^{(a)}(0) = \exp\{\pm[H(x) - H(0)]\}$ with the upper sign for $b \leq x \leq 0$ and the lower one for $0 \leq x \leq a$. Thus, from (2.14),

$$H(x) - H(0) \geq \begin{cases} \alpha_a x & \text{for } 0 \leq x \leq a, \\ \alpha_b x & \text{for } b \leq x \leq 0. \end{cases} \tag{2.15}$$

In the standard setting for energy-driven dynamics, the steepness α of the walls is assumed to *grow* as the parameter playing the role of a (often the inverse temperature) diverges. Here we do not require such a drastic behavior. In fact, α is allowed to *go to zero* (that is, $K_a \rightarrow \infty$) as long as (2.7) and (2.10) remain valid. This generality allows our results to be applicable to the Ehrenfest model. Condition (2.7) limits K_a to grow sub-linearly with a , and (2.10) implies an analogous limitation for K_b as a function of b . Indeed, (2.11) implies that $\mathbb{E}[T_{a \rightarrow 0}^{(a)}] \leq K_q K_a a$ and, hence, the validity of (2.7) means that

$$\frac{K_a}{a} \leq \frac{K_q K_a^2}{\mathbb{E}[T_{a \rightarrow 0}^{(a)}]} \xrightarrow{a \rightarrow \infty} 0. \tag{2.16}$$

Note that, in particular, a family $X^{(a)}$ has 0^+ -SD if K_a is bounded uniformly in a . This is because $\mathbb{E}[T_{a \rightarrow 0}^{(a)}] \geq a \rightarrow \infty$. Likewise, it has 0^- -SD if $\sup_b K_b < \infty$ as long as b diverges with a .

2.4 Main Result and Applications

To state the main result we need one further piece of notation. For $x, y \in \llbracket b, a \rrbracket$, let $\tau_{x \rightarrow x, y}^{(a)} = \sup\{0 < t < T_{x \rightarrow y}^{(a)} : X_x^{(a)}(t) = x\}$ be the instant of the last visit to x before hitting y and $\tilde{T}_{x \rightarrow y}^{(a)} = T_{x \rightarrow y}^{(a)} - \tau_{x \rightarrow x, y}^{(a)}$ the time needed to hit y after last visit to x . The following results apply also to the particular case $b = 0$ —which we call *half well*. In this case—which constitutes, in fact, the building block of our arguments—every condition involving b is understood to be vacuous.

Theorem 1 *Let $X^{(a)}$ be a family of irreducible birth-and-death chains on $\llbracket b, a \rrbracket$. Then:*

1. *By reversibility, $\tilde{T}_{a \rightarrow 0}^{(a)} \stackrel{\mathcal{L}}{=} \tilde{T}_{0 \rightarrow a}^{(a)}$ and $\tilde{T}_{b \rightarrow 0}^{(a)} \stackrel{\mathcal{L}}{=} \tilde{T}_{0 \rightarrow b}^{(b)}$. (More generally, $\tilde{T}_{x \rightarrow y}^{(a)} \stackrel{\mathcal{L}}{=} \tilde{T}_{y \rightarrow x}^{(a)}$ for any $x, y \in \llbracket b, a \rrbracket$.)*
2. *If $X^{(a)}$ has a SD to the left of 0 (0^+ -SD), resp. to the right of 0 (0^- -SD), the random variables $T_{a \rightarrow 0}^{(a)}$, resp. $T_{b \rightarrow 0}^{(a)}$, exhibit cut-off behavior at mean times.*
3. *Assume $X^{(a)}$ satisfies the 0-SD condition and consider the conditions:*

$$\frac{\mathbb{E}[T_{b \rightarrow 0}^{(a)}]}{\mathbb{E}[T_{0 \rightarrow a}^{(a)}]} \xrightarrow{a \rightarrow \infty} 0, \quad \frac{\mathbb{E}[T_{a \rightarrow 0}^{(a)}]}{\mathbb{E}[T_{0 \rightarrow b}^{(a)}]} \xrightarrow{a \rightarrow \infty} 0. \tag{2.17}$$

- (a) *If the leftmost, resp. the rightmost, condition is satisfied, then the random variables $T_{0 \rightarrow a}^{(a)}$, resp. $T_{0 \rightarrow b}^{(a)}$, exhibit escape-time behavior at mean times.*
- (b) *If both conditions are satisfied, the random variables $T_{0 \rightarrow \{a, b\}}^{(a)}$ exhibit escape-time behavior at mean times.*

Note that, for processes with strong drift towards zero, the conditions (2.17) are satisfied if there exist strictly positive constants c_1 and c_2 such that

$$c_1 \leq \frac{\mathbb{E}[T_{a \rightarrow 0}^{(a)}]}{\mathbb{E}[T_{b \rightarrow 0}^{(a)}]} \leq c_2. \tag{2.18}$$

As commented in Sect. 6, a weaker sufficient condition—also based on magnitudes involving trajectories on one side of the well—is obtained by replacing the hitting times in (2.17) by those for the corresponding “half-well” models (see Remark 1 below). In particular, requirements (2.17) are automatically satisfied for symmetric wells.

Let us mention a few applications.

2.4.1 Simple (Non-symmetric) Random Walk

The simplest application is a random walk with transition rates that only depend on the sign of x and are independent of a : $p_x = p^+$ and $q_x = q^+$ for $x > 0$, while p^- and $q_x = q^-$ for $x < 0$. Formulas (2.11) yield, in this case, $K_a = q^+ / (q^+ - p^+)$ and $K_b = p^- / (p^- - q^-)$ (hence $K_q \leq 2$). Thus, the resulting family $X^{(a)}$ has a 0^+ -SD iff $q^+ > p^+$. Likewise, it has a 0^- -SD iff $p^- > q^-$ and $b \rightarrow \infty$ with a . (That is, SD = positive recurrence.) For these walks, the difference between the mean times towards and away from zero is noticeable. Indeed, $\mathbb{E}[T_{a \rightarrow 0}^{(a)}] \sim a / (q^+ - p^+)$ while, for the half well ($b = 0$), $\mathbb{E}[T_{0 \rightarrow a}^{(a)}] \sim (q^+ / p^+)^a$.

2.4.2 Random Walk with Varying Rates

More generally, Theorem 1 applies to random walks with

$$q^+ := \min_{x \in \llbracket 1, a \rrbracket} q_x > \max_{x \in \llbracket 0, a \rrbracket} p_x =: p^+, \quad p^- := \min_{x \in \llbracket b, -1 \rrbracket} p_x > \max_{x \in \llbracket b, -1 \rrbracket} q_x =: q^- \quad (2.19)$$

and b diverging with a . The values of K_a and K_b are as in the previous example and, as there, $\mathbb{E}[T_{a \rightarrow 0}^{(a)}] \leq \text{const} \times a$ and $\mathbb{E}[T_{0 \rightarrow a}^{(a)}] \geq \text{const} \times (q^+ / p^+)^a$ (for $b = 0$). Furthermore, Theorem 1 holds even if the wall has a “flat” bottom. More precisely, it holds if $q_x = p_x = 1/2$ for $x \in \llbracket d_a^-, d_a^+ \rrbracket$ for some $d_a^- \leq 0$ and $d_a^+ > 0$, as long as

$$\frac{(d_a^+)^2}{a} \xrightarrow{a \rightarrow \infty} 0, \quad \frac{(d_a^-)^2}{b} \xrightarrow{a \rightarrow \infty} 0 \quad (2.20)$$

and

$$q^+ := \min_{x \in \llbracket d_a^+, a \rrbracket} q_x > \max_{x \in \llbracket d_a^+, a \rrbracket} p_x =: p^+, \quad p^- := \min_{x \in \llbracket b, d_a^- \rrbracket} p_x > \max_{x \in \llbracket b, d_a^- \rrbracket} q_x =: q^-. \quad (2.21)$$

Indeed, in this case we can take $K_a = d_a^+ + [q^+ / (q^+ - p^+)]$ and $K_b = -d_a^- + [p^- / (p^- - q^-)]$. On the other hand, $\mathbb{E}[T_{a \rightarrow 0}^{(a)}] \geq d_a^+ + a[\bar{q}^+ / (\bar{q}^+ - \bar{p}^+)]$, where $\bar{q}^+ = \max\{q_x : x \in \llbracket d_a^+, a \rrbracket\}$ and $\bar{p}^+ = \min\{p_x : x \in \llbracket d_a^+, a \rrbracket\}$. An analogous bound holds interchanging $a \leftrightarrow b$, $q^+ \leftrightarrow p^-$ and $p^+ \leftrightarrow q^-$. Hence, conditions (2.21) imply the validity of (2.7) and (2.10).

For these examples, the observation of [40]—commented below Definition 1—applies, namely the cut-off of the hitting time at zero is equivalent to the cut-off in the original measure-theoretical sense.

2.4.3 Ehrenfest Model

It was introduced by Paul and Tatiana Ehrenfest in 1907 to support Boltzmann’s ideas by showing a simple example where microscopic reversibility leads to what can be interpreted as macroscopic irreversibility. The model consists in $2N$ particles distributed in two urns, with $N \in \mathbb{N}$. At each unit of time one of the particles is chosen with uniform probability and changed of urn. The process follows the number of particles in one of the urns; a dynamic

that is equivalent to the projection of a random walk on the hypercube $\{-1, 1\}^{2N}$. In this last form, but in continuous time, the cut-off aspects of the model have been studied in [28]. The escape behavior has been analyzed in [6], in terms of the initial urn model, and in [11, 12] in its random-walk version for continuous time.

Our framework applies to the initial discrete-time model. We identify a with N and shift the urn counting by $-a$, so to obtain a model with drift towards zero. The resulting family $X^{(a)}$ has state space $\llbracket -a, a \rrbracket$ and transition probabilities

$$p_x = \frac{a - x}{2a} \quad \text{and} \quad q_x = \frac{a + x}{2a}. \tag{2.22}$$

Unlike our previous examples, both transition rates depends on a and have a drift-less limit ($p_x = q_x = 1/2$) when $a \rightarrow \infty$. Furthermore, some elementary calculations (see [8]) show that $K_a = K_{-a} = 1/\pi^{(a)}(0) \sim \sqrt{a}$. The model has a strong drift, however, because $\mathbb{E}[T_{a \rightarrow 0}^{(a)}] = \mathbb{E}[T_{-a \rightarrow 0}^{(a)}] \sim a \log a$.

3 Sufficient Conditions for Cut-off and Escape Behavior

In this section we develop the sufficient conditions to be used in the sequel to prove the behavior of the variables in Theorem 1. Here we adopt a rather general set-up, not restricted to birth-and-death processes.

3.1 Cut-off Behavior

The following sufficient condition for a family of random variables $U^{(a)}$ to exhibit cut-off behavior in the sense of Definition 1 was first pointed out in [40]:

Proposition 1 *A family of random variables $U^{(a)}$ exhibit cut-off at mean times if*

$$\lim_{a \rightarrow \infty} \text{Var} \left(\frac{U^{(a)}}{\mathbb{E}[U^{(a)}]} \right) = 0. \tag{3.1}$$

The proof is a direct application of Tchebyshev inequality: For $Z = 1 - U^{(a)}/\mathbb{E}[U^{(a)}]$, we have that $\mathbb{P}(|Z| > \varepsilon) \leq \mathbb{E}[Z^2]/\varepsilon = \text{Var}(Z)/\varepsilon$. This simple observation allows the determination of cut-off behavior without a precise estimation of the cut-off times $\mathbb{E}[U^{(a)}]$.

3.2 Escape-time Behavior

We adapt the “pathwise approach” introduced in [21] to a general setting. We consider Markov chains $X^{(a)}(t)$ on countable alphabets \mathcal{A}_a , and we distinguish a (“low”) state $\ell \in \mathcal{A}_a$, (“high”) regions $\mathcal{H}_a \subset \mathcal{A}_a$, with $\ell \notin \mathcal{H}_a$ and hitting times

$$T_{x \rightarrow \mathcal{H}_a}^{(a)} := \inf_{h \in \mathcal{H}_a} \inf \{ t > 0 : X_\ell^{(a)}(t) = h \}. \tag{3.2}$$

The mechanism through which the variables $T_{x \rightarrow \mathcal{H}_a}^{(a)}$ develop an asymptotically exponential law is the existence of a much shorter time scale for excursions in the direction $\mathcal{H}_a \rightarrow \ell$ than vice-versa. Let us be more precise.

Definition 3 We say that the mean time from \mathcal{H}_a to ℓ is much shorter than that from ℓ to \mathcal{H}_a , and we write

$$\mathbb{E}[T_{\mathcal{H}_a \rightarrow \ell}^{(a)}] \ll_{\text{ms}} \mathbb{E}[T_{\ell \rightarrow \mathcal{H}_a}^{(a)}], \tag{3.3}$$

if the following conditions are satisfied:

1. Different time scales:

$$\lim_{a \rightarrow \infty} \frac{\sup_{x \in \mathcal{A}_a} \mathbb{E}[T_{x \rightarrow \ell}^{(a)}]}{\mathbb{E}[T_{\ell \rightarrow \mathcal{H}_a}^{(a)}]} = 0. \tag{3.4}$$

2. Uniform integrability of the sequence

$$S^{(a)} := \frac{T_{\ell \rightarrow \mathcal{H}_a}^{(a)}}{\mathbb{E}[T_{\ell \rightarrow \mathcal{H}_a}^{(a)}]}. \tag{3.5}$$

This means that for all $\varepsilon > 0$ there must exist $L_\varepsilon > 0$ such that

$$\mathbb{E}[S^{(a)}; S^{(a)} > L_\varepsilon] < \varepsilon, \quad \forall a. \tag{3.6}$$

These conditions imply escape behavior:

Theorem 2 Let $X^{(a)}(t)$ be a family of irreducible and positive recurrent Markov chains on a countable alphabet \mathcal{A}_a . If $\ell \in \mathcal{A}_a$ and $\mathcal{H}_a \subset \mathcal{A}_a$ are such that $\mathbb{E}[T_{\mathcal{H}_a \rightarrow \ell}^{(a)}] \ll_{\text{ms}} \mathbb{E}[T_{\ell \rightarrow \mathcal{H}_a}^{(a)}]$, then the family $T_{\ell \rightarrow \mathcal{H}_a}^{(a)}$ exhibits escape-time behavior at mean times.

Let us first summarize the central idea of the proof. It amounts to exhibit the asymptotic factorization

$$\mathbb{P}\left(\frac{T_{\ell \rightarrow \mathcal{H}_a}^{(a)}}{\mathbb{E}[T_{\ell \rightarrow \mathcal{H}_a}^{(a)}]} > s + t\right) - \mathbb{P}\left(\frac{T_{\ell \rightarrow \mathcal{H}_a}^{(a)}}{\mathbb{E}[T_{\ell \rightarrow \mathcal{H}_a}^{(a)}]} > s\right)\mathbb{P}\left(\frac{T_{\ell \rightarrow \mathcal{H}_a}^{(a)}}{\mathbb{E}[T_{\ell \rightarrow \mathcal{H}_a}^{(a)}]} > t\right) \xrightarrow{a \rightarrow \infty} 0. \tag{3.7}$$

This follows from the existence, by condition (3.4), of a time scale that is intermediate between the hitting times in both directions. Indeed,

$$\Delta_a = \sqrt{\mathbb{E}[T_{\ell \rightarrow \mathcal{H}_a}^{(a)}] \sup_{x \in \mathcal{A}_a} \mathbb{E}[T_{x \rightarrow \ell}^{(a)}]} \tag{3.8}$$

is such that

$$\beta_a := \frac{\Delta_a}{\mathbb{E}[T_{\ell \rightarrow \mathcal{H}_a}^{(a)}]} \xrightarrow{a \rightarrow \infty} 0 \tag{3.9}$$

and

$$\frac{\sup_{x \in \mathcal{A}_a} \mathbb{E}[T_{x \rightarrow \ell}^{(a)}]}{\Delta_a} \xrightarrow{a \rightarrow \infty} 0. \tag{3.10}$$

Note that, by Markov inequality, this last equation implies that

$$\mathbb{P}(\text{walk visits } \ell \text{ in an interval of length } \Delta_a) \xrightarrow{a \rightarrow \infty} 1. \tag{3.11}$$

If a process started at ℓ has not hit the region \mathcal{H}_a after $s\mathbb{E}[T_{\ell \rightarrow \mathcal{H}_a}^{(a)}]$ time units, then, due to (3.11), it will almost surely fall down to ℓ within an interval of length Δ_a . Once ℓ is visited, the process recovers the initial law, by Markovianness. Therefore,

$$\begin{aligned} &\mathbb{P}(T_{\ell \rightarrow \mathcal{H}_a}^{(a)} > (s + t)\mathbb{E}[T_{\ell \rightarrow \mathcal{H}_a}^{(a)}]) \\ &\approx \mathbb{P}(T_{\ell \rightarrow \mathcal{H}_a}^{(a)} > s\mathbb{E}[T_{\ell \rightarrow \mathcal{H}_a}^{(a)}])\mathbb{P}(T_{\ell \rightarrow \mathcal{H}_a}^{(a)} > (t - \Delta_a)\mathbb{E}[T_{\ell \rightarrow \mathcal{H}_a}^{(a)}]). \end{aligned} \tag{3.12}$$

As Δ_a is negligible with respect to $\mathbb{E}[T_{\ell \rightarrow \mathcal{H}_a}^{(a)}]$ [condition (3.9)], the factorization (3.7) follows.

This argument is formalized through a number of technical results contained in the following lemmas. Let

$$T_\ell^s := \inf\{t \geq s\mathbb{E}[T_{\ell \rightarrow \mathcal{H}_a}^{(a)}] : X_\ell^{(a)}(t) = \ell\}, \tag{3.13}$$

denote the first return time to ℓ after $s\mathbb{E}[T_{\ell \rightarrow \mathcal{H}_a}^{(a)}]$, and

$$S_\ell^s := \frac{T_\ell^s}{\mathbb{E}[T_{\ell \rightarrow \mathcal{H}_a}^{(a)}]}. \tag{3.14}$$

These times are well defined: since, as we assume the chain to be positively recurrent, every mean hitting time is finite.

Lemma 1 *Under the hypotheses of Theorem 2,*

$$\lim_{a \rightarrow \infty} \mathbb{P}(S_\ell^s > s + \beta_a) = 0. \tag{3.15}$$

Proof Define $t_a := s\mathbb{E}[T_{\ell \rightarrow \mathcal{H}_a}^{(a)}]$, $s_a := \lceil t_a \rceil$, $r_a := \lfloor t_a + \Delta_a \rfloor$ and $I_a := \{s_a, \dots, r_a\}$, where $\lfloor x \rfloor$ and $\lceil x \rceil$ denote respectively the floor and ceiling functions of x . Partitioning over all possible values of $X_{t_a}^{(a)}(s_a)$, we get

$$\begin{aligned} \mathbb{P}(S_\ell^s > s + \beta_a) &= \mathbb{P}(X_\ell^{(a)}(k) \neq \ell, \forall k \in I_a) \\ &= \sum_{x \in \mathcal{A}_a} \mathbb{P}(X_\ell^{(a)}(k) \neq \ell, \forall k \in I_a \mid X_\ell^{(a)}(s_a) = x)\mathbb{P}(X_\ell^{(a)}(s_a) = x) \\ &\leq \sup_{x \in \mathcal{A}_a} \mathbb{P}(X_\ell^{(a)}(k) \neq \ell, \forall k \in I_a \mid X_\ell^{(a)}(s_a) = x) \sum_{x \in \mathcal{A}_a} \mathbb{P}(X_\ell^{(a)}(s_a) = x) \\ &= \sup_{x \in \mathcal{A}_a} \mathbb{P}(T_{x \rightarrow \ell}^{(a)} > \Delta_a). \end{aligned} \tag{3.16}$$

Hence, using Markov inequality,

$$\mathbb{P}(S_\ell^s > s + \beta_a) \leq \frac{\sup_{x \in \mathcal{A}_a} \mathbb{E}[T_{x \rightarrow \ell}^{(a)}]}{\Delta_a}, \tag{3.17}$$

which tends to zero due to (3.4). □

Lemma 2 *Under the hypotheses of Theorem 2, the following inequalities hold:*

$$\mathbb{P}(S^{(a)} > s + t, S_\ell^s \leq s + \beta_a) \geq \mathbb{P}(S^{(a)} > s + \beta_a, S_\ell^s \leq s + \beta_a)\mathbb{P}(S^{(a)} > t) \tag{3.18}$$

and

$$\mathbb{P}(S^{(a)} > s + t, S_\ell^s \leq s + \beta_a) \leq \mathbb{P}(S^{(a)} > s)\mathbb{P}(S^{(a)} > t - \beta_a). \tag{3.19}$$

Proof We start with the following identity, obtained by portioning over all possible values of T_ℓ^s ,

$$\begin{aligned} &\mathbb{P}(S^{(a)} > s + t, S_\ell^s \leq s + \beta_a) \\ &= \sum_{k \in I_a} \mathbb{P}(S^{(a)} > s + t, T_\ell^s = k) = \sum_{k \in I_a} \mathbb{P}(S^{(a)} > s + t, S^{(a)} > s, T_\ell^s = k) \\ &= \sum_{k \in I_a} \mathbb{P}(S^{(a)} > s + t \mid S^{(a)} > s, T_\ell^s = k)\mathbb{P}(S^{(a)} > s, T_\ell^s = k). \end{aligned} \tag{3.20}$$

The Markov property implies that

$$\mathbb{P}(S^{(a)} > s + t \mid S^{(a)} > s, T_\ell^s = k) = \mathbb{P}\left(S^{(a)} > s + t - \frac{k}{\mathbb{E}[T_{\ell \rightarrow \mathcal{H}_a}^{(a)}]}\right), \tag{3.21}$$

for all $k \in I_a$. The rightmost expression is bounded below by its value at $k = s_a$, and bounded above by its value at $k = s_a + \Delta_a$. Hence,

$$\mathbb{P}(S^{(a)} > t) \leq \mathbb{P}(S^{(a)} > s + t \mid S^{(a)} > s, T_\ell^s = k) \leq \mathbb{P}(S^{(a)} > t - \beta_a). \tag{3.22}$$

To prove (3.18) we combine (3.20) with the leftmost bound in (3.22). We obtain:

$$\begin{aligned} \mathbb{P}(S^{(a)} > s + t, S_\ell^s \leq s + \beta_a) &\geq \mathbb{P}(S^{(a)} > t) \sum_{k \in I_a} \mathbb{P}(S^{(a)} > s, T_\ell^s = k) \\ &= \mathbb{P}(S^{(a)} > t)\mathbb{P}(S^{(a)} > s, S_\ell^s \leq s + \beta_a) \\ &\geq \mathbb{P}(S^{(a)} > t)\mathbb{P}(S^{(a)} > s + \beta_a, S_\ell^s \leq s + \beta_a). \end{aligned} \tag{3.23}$$

Likewise, (3.19) follows from (3.20), the rightmost bound in (3.22):

$$\begin{aligned} \mathbb{P}(S^{(a)} > s + t, S_\ell^s \leq s + \beta_a) &\leq \mathbb{P}(S^{(a)} > t - \beta_a) \sum_{k \in I_a} \mathbb{P}(S^{(a)} > s, T_\ell^s = k) \\ &\leq \mathbb{P}(S^{(a)} > t - \beta_a)\mathbb{P}(S^{(a)} > s). \end{aligned} \tag{3.24}$$

□

Lemma 3 Assume the hypothesis of Theorem 2 and let S be the weak limit of a subsequence of $S^{(a)}$. Then,

$$\mathbb{P}(S > s + t) = \mathbb{P}(S > s)\mathbb{P}(S > t) \tag{3.25}$$

for all s and t such that s , t and $s + t$ are continuity points of the distribution function of S .

Proof The previous lemmas remain valid for a varying through the subsequence index. For notational simplicity we keep using a for the latter and denote $S^{(a)}$ the converging subsequence. Identity (3.25) is proven by decomposing it into an upper and a lower bound.

Proof of the upper bound We write:

$$\mathbb{P}(S^{(a)} > s + t) - \mathbb{P}(S^{(a)} > s)\mathbb{P}(S^{(a)} > t) = A_a + B_a \tag{3.26}$$

with

$$A_a = \mathbb{P}(S^{(a)} > s + t) - \mathbb{P}(S^{(a)} > s)\mathbb{P}(S^{(a)} > t - \beta_a) \tag{3.27}$$

and

$$B_a = \mathbb{P}(S^{(a)} > s)[\mathbb{P}(S^{(a)} > t - \beta_a) - \mathbb{P}(S^{(a)} > t)]. \tag{3.28}$$

By (3.19),

$$\begin{aligned} A_a &\leq \mathbb{P}(S^{(a)} > s + t) - \mathbb{P}(S^{(a)} > s + t, S_\ell^s \leq s + \beta_a) \\ &= \mathbb{P}(S^{(a)} > s + t, S_\ell^s > s + \beta_a). \end{aligned} \tag{3.29}$$

Thus, by Lemma 1,

$$\limsup_{a \rightarrow \infty} A_a \leq 0. \tag{3.30}$$

On the other hand, as t is a point of continuity and $\beta_a \rightarrow 0$ [condition (3.9)], the weak convergence of the sequence implies that

$$\lim_{a \rightarrow \infty} [\mathbb{P}(S^{(a)} > t - \beta_a) - \mathbb{P}(S^{(a)} > t)] = 0. \tag{3.31}$$

Thus

$$\lim_{a \rightarrow \infty} B_a = 0. \tag{3.32}$$

From (3.26), (3.30), (3.32) and the weak convergence of $S^{(a)}$ we conclude that

$$\mathbb{P}(S > s + t) - \mathbb{P}(S > s)\mathbb{P}(S > t) \leq 0. \tag{3.33}$$

Proof of the lower bound This time we write

$$\mathbb{P}(S^{(a)} > s + t) - \mathbb{P}(S^{(a)} > s)\mathbb{P}(S^{(a)} > t) = C_a + \mathbb{P}(S^{(a)} > t)D_a \tag{3.34}$$

with

$$C_a = \mathbb{P}(S^{(a)} > s + t) - \mathbb{P}(S^{(a)} > s + \beta_a, S_\ell^s \leq s + \beta_a)\mathbb{P}(S^{(a)} > t) \tag{3.35}$$

and

$$D_a = \mathbb{P}(S^{(a)} > s + \beta_a, S_\ell^s \leq s + \beta_a) - \mathbb{P}(S^{(a)} > s). \tag{3.36}$$

By (3.18),

$$C_a \geq \mathbb{P}(S^{(a)} > s + t, S_\ell^s > s + \beta_a) \geq 0. \tag{3.37}$$

We further decompose D_a by subtracting and adding $\mathbb{P}(S^{(a)} > s + \beta_a)$. We obtain

$$D_a = -\mathbb{P}(S^{(a)} > s + \beta_a, S_\ell^s > s + \beta_a) + [\mathbb{P}(S^{(a)} > s + \beta_a) - \mathbb{P}(S^{(a)} > s)]. \tag{3.38}$$

Both terms converge to zero; the first one by Lemma 1 and the second by continuity at s and condition (3.9). Therefore,

$$\lim_{a \rightarrow \infty} D_a = 0. \tag{3.39}$$

Because of the weak convergence of $S^{(a)}$, (3.34), (3.37) and (3.39) imply that

$$\mathbb{P}(S > s + t) - \mathbb{P}(S > s)\mathbb{P}(S > t) \geq 0. \tag{3.40}$$

□

Proof of Theorem 2 It follows from the preceding lemma and some general considerations. We first remark that the sequence $S^{(a)}$ is uniformly tight because $\mathbb{E}[S^{(a)}] = 1$. Indeed, using Markov inequality,

$$\mathbb{P}(S^{(a)} > t) \leq \frac{\mathbb{E}[S^{(a)}]}{t} = \frac{1}{t} \xrightarrow{t \rightarrow \infty} 0. \tag{3.41}$$

It follows (see, e.g., Theorem 4.4.3. in [24]) that every sub-sequence $S^{(a')}$ of $S^{(a)}$ admits a sub-sequence $S^{(a'')}$ that converges in law. We only have to prove that there exists a unique limit law, namely $\exp(1)$. Let S be the limit of one of these convergent subsequences. By Lemma 3

$$\mathbb{P}(S > s + t) = \mathbb{P}(S > s)\mathbb{P}(S > t), \tag{3.42}$$

for all continuity points of F_S , the distribution function of S . These continuity points are dense in \mathbb{R} because F_S , being increasing, has at most a denumerable number of discontinuities. Thus, (3.42) holds for all s and t .

It remains to show that $\mathbb{E}[S] = 1$ to prove that S can have only one law, namely exponential with mean 1. It is here that we invoke the hypothesis of uniform integrability of the sequence $S^{(a)}$. Indeed, by Theorem 5.4 of [10], the fact that $S^{(a'')}$ is a weakly convergent sequence of uniformly integrable mean-one random variables, implies that

$$\mathbb{E}[S] = \lim_{a'' \rightarrow \infty} \mathbb{E}[S^{(a'')}] = 1. \tag{3.43}$$

Since every sub-sequence of $S^{(a)}$ admits a sub-sequence that weakly converges to a unique limit S , thus $S^{(a)}$ also converges to the same limit. □

4 Mean Hitting Times for Birth-and-Death Processes

The estimation needed to apply the criteria of the previous section to birth-and-death processes relies on explicit formulas of mean hitting times available for these processes. We apply the standard technique of establishing a difference equation for consecutive mean times that is solved by iteration (see for instance [32] Chap. XIV). Throughout this section, to shorten formulas we adopt the conventions $\prod_{j+1}^j := 1$ and $\sum_a^{a-1} := 0$.

We consider an irreducible birth-and-death process X on a finite interval $[[b, a]] \subset \mathbb{Z}$ with transition rates $0 < p(x, x + 1) =: p_x, b \leq x \leq a - 1; 0 < q(x, x - 1) =: q_x, b + 1 \leq x \leq a$, and $r_x := 1 - p_x - q_x$. The invariant measure for such a process is also reversible and can be written in the forms [cf. (2.3)]:

$$\pi^{(a)}(x) = \prod_{i=b+1}^x \frac{p_{i-1}}{q_i} \pi^{(a)}(b) = \prod_{i=x+1}^a \frac{q_i}{p_{i-1}} \pi^{(a)}(a) \tag{4.1}$$

for $b \leq x \leq a$. Hence, for $k < l$,

$$\prod_{i=k+1}^l \frac{p_{i-1}}{q_i} = \prod_{i=k+1}^l \frac{q_i}{p_{i-1}} = \frac{\pi^{(a)}(l)}{\pi^{(a)}(k)}. \tag{4.2}$$

Proposition 2 For the preceding birth-and-death process, the following identities hold:

1. For $b \leq n < j \leq a$,

$$\mathbb{E}[T_{j \rightarrow n}] = \sum_{k=n+1}^j \frac{\pi(\llbracket k, a \rrbracket)}{q_k \pi(k)}, \tag{4.3}$$

$$\mathbb{E}[T_{j \rightarrow n}^2] = \sum_{k=n+1}^j \frac{2}{q_k \pi(k)} \sum_{l=k}^a \mathbb{E}[T_{l \rightarrow n}] \pi(l) - \mathbb{E}[T_{j \rightarrow n}]. \tag{4.4}$$

2. For $b \leq j < n \leq a$,

$$\mathbb{E}[T_{j \rightarrow n}] = \sum_{k=j}^{n-1} \frac{\pi(\llbracket b, k \rrbracket)}{p_k \pi(k)}, \tag{4.5}$$

$$\mathbb{E}[T_{j \rightarrow n}^2] = \sum_{k=j}^{n-1} \frac{2}{p_k \pi(k)} \sum_{l=b}^k \mathbb{E}[T_{l \rightarrow n}] \pi(l) - \mathbb{E}[T_{j \rightarrow n}], \tag{4.6}$$

$$\mathbb{E}[T_{j \rightarrow n}] + \mathbb{E}[T_{n \rightarrow j}] = \sum_{k=j+1}^n \frac{1}{q_k \pi(k)}. \tag{4.7}$$

3. For $b \leq m < j < n \leq a$,

$$\mathbb{E}[T_{j \rightarrow \{m, n\}}] = \frac{\mathbb{E}[T_{n \rightarrow m}] \mathbb{E}[T_{j \rightarrow n}] - \mathbb{E}[T_{m \rightarrow n}] \mathbb{E}[T_{n \rightarrow j}]}{\mathbb{E}[T_{m \rightarrow n}] + \mathbb{E}[T_{n \rightarrow m}]} \tag{4.8}$$

$$= \frac{\mathbb{E}[T_{m \rightarrow n}] \mathbb{E}[T_{j \rightarrow m}] - \mathbb{E}[T_{n \rightarrow m}] \mathbb{E}[T_{m \rightarrow j}]}{\mathbb{E}[T_{m \rightarrow n}] + \mathbb{E}[T_{n \rightarrow m}]}. \tag{4.9}$$

Proof For all cases, the equation is obtained from the following decomposition.

Claim: Let $\mathcal{K} \subset \llbracket a, b \rrbracket$ and $j \notin \mathcal{K}$, $b \leq j \leq a$. Then, for any function F ,

$$\mathbb{E}[F(T_{j \rightarrow \mathcal{K}})] = p_j \mathbb{E}[F(T_{j+1 \rightarrow \mathcal{K}} + 1)] + q_j \mathbb{E}[F(T_{j-1 \rightarrow \mathcal{K}} + 1)] + r_j \mathbb{E}[F(T_{j \rightarrow \mathcal{K}} + 1)] \tag{4.10}$$

with the conventions $T_{a+1 \rightarrow \mathcal{K}}, T_{b-1 \rightarrow \mathcal{K}} := 0$ and $T_{i \rightarrow \mathcal{K}} := 0$ if $i \in \mathcal{K}$.

Indeed, decomposing according to the first step of the process,

$$\begin{aligned} \mathbb{E}[F(T_{j \rightarrow \mathcal{K}})] &= p_j \mathbb{E}[F(T_{j \rightarrow \mathcal{K}}) \mid X(1) = j + 1] + q_j \mathbb{E}[F(T_{j \rightarrow \mathcal{K}}) \mid X(1) = j - 1] \\ &\quad + r_j \mathbb{E}[F(T_{j \rightarrow \mathcal{K}} + 1) \mid X(1) = j]. \end{aligned} \tag{4.11}$$

In the three cases $i = j - 1, j, j + 1$,

$$\begin{aligned}
 \mathbb{E}[F(T_{j \rightarrow \mathcal{K}}) \mid X(1) = i] &= \sum_{k \geq 1} F(k) \mathbb{P}(T_{j \rightarrow \mathcal{K}} = k \mid X(1) = i) \\
 &= \sum_{k \geq 1} F(k) \mathbb{P}(T_{i \rightarrow \mathcal{K}} = k - 1) \\
 &= \sum_{k \geq 0} F(k + 1) \mathbb{P}(T_{i \rightarrow \mathcal{K}} = k) \\
 &= \mathbb{E}[F(T_{i \rightarrow \mathcal{K}} + 1)].
 \end{aligned}
 \tag{4.12}$$

The second equality is due to Markovianness. The claim follows from (4.11) and (4.12).

Proof of (4.3) and (4.5) Applying (4.10) for $F(T) = T$ and $\mathcal{K} = \{n\}$ we arrive to the difference equation

$$\mathbb{E}[T_{j \rightarrow n}] = \frac{p_j}{p_j + q_j} \mathbb{E}[T_{j+1 \rightarrow n}] + \frac{q_j}{p_j + q_j} \mathbb{E}[T_{j-1 \rightarrow n}] + \frac{1}{p_j + q_j}
 \tag{4.13}$$

valid for $j = b + 1, \dots, a - 1$ and subject to the boundary conditions:

$$\begin{aligned}
 \mathbb{E}[T_{b \rightarrow n}] &= \mathbb{E}[T_{b+1 \rightarrow n}] + \frac{1}{p_b}, \\
 \mathbb{E}[T_{n \rightarrow n}] &= 0, \\
 \mathbb{E}[T_{a \rightarrow n}] &= \mathbb{E}[T_{a-1 \rightarrow n}] + \frac{1}{q_a}.
 \end{aligned}
 \tag{4.14}$$

To prove (4.3) it is useful to rewrite (4.13) in the form

$$D_k - D_{k-1} = B_k(D_{k+1} - D_k) + \epsilon_k
 \tag{4.15}$$

with $D_j = \mathbb{E}[T_{j \rightarrow n}]$, $B_j = p_j/q_j$ and $\epsilon_j = 1/q_j$. This equation is easily solved by iteration, yielding

$$D_k - D_{k-1} = \prod_{i=k}^{a-1} B_i(D_a - D_{a-1}) + \sum_{l=k}^{a-1} \epsilon_l \prod_{i=k}^{l-1} B_i,
 \tag{4.16}$$

and, thus,

$$D_j = D_a - \sum_{k=j+1}^a \left(\prod_{i=k}^{a-1} B_i(D_a - D_{a-1}) + \sum_{l=k}^{a-1} \epsilon_l \prod_{i=k}^{l-1} B_i \right).
 \tag{4.17}$$

Upon application of the last two conditions in (4.14):

$$\begin{aligned}
 D_a - D_{a-1} &= \epsilon_a, \\
 D_n &= 0,
 \end{aligned}
 \tag{4.18}$$

we finally obtain

$$D_j = \sum_{k=n+1}^j \sum_{l=k}^a \epsilon_l \prod_{i=k}^{l-1} B_i,
 \tag{4.19}$$

that is,

$$\mathbb{E}[T_{j \rightarrow n}] = \sum_{k=n+1}^j \frac{1}{q_k} \sum_{l=k}^a \prod_{i=k+1}^l \frac{p_{i-1}}{q_i}. \tag{4.20}$$

This is, in fact, expression (4.3) due to identity (4.2).

The proof of (4.5) is analogous, but inverting the direction of iteration. We write (4.13) in the form

$$D_{k+1} - D_k = \tilde{B}_k(D_k - D_{k-1}) - \tilde{\epsilon}_k \tag{4.21}$$

with $\tilde{B}_j = q_j/p_j$ and $\tilde{\epsilon}_j = 1/p_j$. The solution is now

$$D_j = D_b + \sum_{k=b}^{j-1} \left(\prod_{i=b+1}^k \tilde{B}_i(D_{b+1} - D_b) - \sum_{l=b+1}^k \tilde{\epsilon}_l \prod_{i=l+1}^k \tilde{B}_i \right). \tag{4.22}$$

The first two conditions in (4.14):

$$\begin{aligned} D_{b+1} - D_b &= -\tilde{\epsilon}_b, \\ D_n &= 0, \end{aligned} \tag{4.23}$$

lead to

$$D_j = \sum_{k=j}^{n-1} \sum_{l=b}^k \tilde{\epsilon}_l \prod_{i=l+1}^k \tilde{B}_i. \tag{4.24}$$

In terms of the original quantities this is equal to

$$\mathbb{E}[T_{j \rightarrow n}] = \sum_{k=j}^{n-1} \frac{1}{p_k} \sum_{l=0}^k \prod_{i=l+1}^k \frac{q_i}{p_{i-1}}, \tag{4.25}$$

which, together with (4.2), leads to (4.5).

Proof of (4.4) and (4.6) We apply (4.10) for $F(T) = T^2$ and $\mathcal{K} = \{n\}$ to arrive to the difference equation

$$\mathbb{E}[T_{j \rightarrow n}^2] = \frac{p_j}{p_j + q_j} \mathbb{E}[T_{j+1 \rightarrow n}^2] + \frac{q_j}{p_j + q_j} \mathbb{E}[T_{j-1 \rightarrow n}^2] + \frac{2\mathbb{E}[T_{j \rightarrow n}] - 1}{p_j + q_j}, \tag{4.26}$$

$j \in \llbracket b + 1, a - 1 \rrbracket$, plus the boundary conditions:

$$\begin{aligned} \mathbb{E}[T_{b \rightarrow n}^2] &= \mathbb{E}[T_{b+1 \rightarrow n}^2] + \frac{2\mathbb{E}[T_{b \rightarrow n}] - 1}{p_b}, \\ \mathbb{E}[T_{n \rightarrow n}^2] &= 0, \\ \mathbb{E}[T_{a \rightarrow n}^2] &= \mathbb{E}[T_{a-1 \rightarrow n}^2] + \frac{2\mathbb{E}[T_{a \rightarrow n}] - 1}{q_a}. \end{aligned} \tag{4.27}$$

If we now substitute $D_j = \mathbb{E}[T_{j \rightarrow n}^2]$, $B_j = p_j/q_j$, $\tilde{B}_j = q_j/p_j$, $\epsilon_j = (2\mathbb{E}[T_{j \rightarrow n}] - 1)/q_j$ and $\tilde{\epsilon}_j = (2\mathbb{E}[T_{j \rightarrow n}] - 1)/p_j$ we recover (4.15) and (4.21) and the boundary conditions (4.18)

and (4.23). The corresponding solutions (4.19) and (4.24) yield

$$\mathbb{E}[T_{j \rightarrow n}^2] = \begin{cases} \sum_{k=n+1}^j \frac{1}{q_k} \sum_{l=k}^a (2\mathbb{E}[T_{l \rightarrow n}] - 1) \prod_{i=k+1}^l \frac{p_{i-1}}{q_i}, & b \leq n < j \leq a, \\ \sum_{k=j}^{n+1} \frac{1}{p_k} \sum_{l=b}^k (2\mathbb{E}[T_{l \rightarrow n}] - 1) \prod_{i=l+1}^k \frac{q_i}{p_{i-1}}, & b \leq j < n \leq a. \end{cases} \tag{4.28}$$

The first and second lines become, respectively, (4.4) and (4.6) upon resorting to (4.2) and (4.20)/(4.25).

Proof of (4.7) From (4.3), (4.5) and the reversibility relation $\pi(x)p_x = \pi(x + 1)q_{x+1}$, we have:

$$\mathbb{E}[T_{j \rightarrow n}] + \mathbb{E}[T_{n \rightarrow j}] = \sum_{k=j+1}^n \frac{\pi(\llbracket b, k - 1 \rrbracket) + \pi(\llbracket k, a \rrbracket)}{q_k \pi(k)} \tag{4.29}$$

which is, precisely, (4.7) because $\pi(\llbracket b, a \rrbracket) = 1$.

Proof of (4.8) and (4.9) The application of (4.10) for $F(T) = T$ and $\mathcal{K} = \{m, n\}$ leads to the difference equation (4.13) with n replaced by $\{m, n\}$. The equation is valid for $m < j < n$ and is supplemented by the boundary conditions

$$\mathbb{E}[T_{n \rightarrow n}] = 0 = \mathbb{E}[T_{m \rightarrow m}]. \tag{4.30}$$

The substitutions $D_j = \mathbb{E}[T_{j \rightarrow \{m, n\}}]$, $B_j = p_j/q_j$ and $\epsilon_j = 1/q_j$ lead to the same identity (4.15) which, iterated from $k = n$ downwards, yields

$$D_j = D_n - \sum_{k=j+1}^n \left(\prod_{i=k}^{n-1} B_i (D_n - D_{n-1}) + \sum_{l=k}^{n-1} \epsilon_l \prod_{i=k}^{l-1} B_i \right). \tag{4.31}$$

Once imposed the condition $D_n = 0$, the solution takes the form

$$D_j = D_{n-1} F_j - G_j, \tag{4.32}$$

with

$$F_j = \sum_{k=j+1}^n \prod_{i=k}^{n-1} B_i, \tag{4.33}$$

$$G_j = \sum_{k=j+1}^n \sum_{l=k}^{n-1} \epsilon_l \prod_{i=k}^{l-1} B_i. \tag{4.34}$$

The remaining condition $D_m = 0$ implies, then,

$$D_j = \frac{G_m}{F_m} F_j - G_j. \tag{4.35}$$

Replacing $B_i = p_i/q_i$, $\epsilon_j = 1/q_j$ and using (4.2) we get

$$F_j = \sum_{k=j+1}^n \frac{q_n \pi(n)}{q_k \pi(k)} \tag{4.36}$$

and

$$G_j = \sum_{k=j+1}^n \frac{\pi(\llbracket k, n-1 \rrbracket)}{q_k \pi(k)} = \sum_{k=j+1}^n \frac{\pi(\llbracket k, a \rrbracket) - \pi(\llbracket n, a \rrbracket)}{q_k \pi(k)}. \tag{4.37}$$

We now resort to (4.3) and (4.7) to conclude:

$$F_j = q_n \pi(n) [\mathbb{E}[T_{j \rightarrow n}] + \mathbb{E}[T_{n \rightarrow j}]], \tag{4.38}$$

$$G_j = \mathbb{E}[T_{n \rightarrow j}] - \pi(\llbracket n, a \rrbracket) [\mathbb{E}[T_{j \rightarrow n}] + \mathbb{E}[T_{n \rightarrow j}]]. \tag{4.39}$$

Identity (4.8) is obtained by replacing these two equalities (and their $j = m$ version) into (4.35). Identity (4.9) can, of course, be obtained in a similar fashion iterating (4.21) up from $k = m$. Alternatively, it follows from the fact that the numerators of (4.8) and (4.9) are equal because their difference is

$$\begin{aligned} & \mathbb{E}[T_{n \rightarrow m}] (\mathbb{E}[T_{m \rightarrow j}] + \mathbb{E}[T_{j \rightarrow n}]) - \mathbb{E}[T_{m \rightarrow n}] (\mathbb{E}[T_{n \rightarrow j}] + \mathbb{E}[T_{j \rightarrow m}]) \\ &= \mathbb{E}[T_{n \rightarrow m}] \mathbb{E}[T_{m \rightarrow n}] - \mathbb{E}[T_{m \rightarrow n}] \mathbb{E}[T_{n \rightarrow m}] = 0. \end{aligned} \tag{4.40}$$

□

Next we list two useful consequences of the previous proposition.

Corollary 1 *Consider the process of Proposition 2. Then, for $b + 1 \leq x \leq a$,*

$$\mathbb{E}[T_{x \rightarrow x-1}^2] = \frac{2}{q_x \pi(x)} \sum_{c=x}^a \frac{\pi(\llbracket c, a \rrbracket)^2}{q_c \pi(c)} - \mathbb{E}[T_{x \rightarrow x-1}], \tag{4.41}$$

and, for $b \leq j < n \leq a$,

$$\mathbb{E}[T_{j \rightarrow n}^2] \leq 2\mathbb{E}[T_{j \rightarrow n}]^2 + 2\mathbb{E}[T_{b \rightarrow j}] \mathbb{E}[T_{j \rightarrow n}] - \mathbb{E}[T_{j \rightarrow n}]. \tag{4.42}$$

Proof Equation (4.41) is an immediate consequence of (4.4) and (4.3). Inequality (4.42) is obtained from (4.6) and (4.5):

$$\begin{aligned} \mathbb{E}[T_{j \rightarrow n}^2] &\leq \sum_{k=j}^{n-1} \frac{2}{p_k \pi(k)} \sum_{l=b}^k (\mathbb{E}[T_{l \rightarrow j}] + \mathbb{E}[T_{j \rightarrow n}]) \pi(l) - \mathbb{E}[T_{j \rightarrow n}] \\ &= \sum_{k=j}^{n-1} \frac{2}{p_k \pi(k)} \sum_{l=b}^k \mathbb{E}[T_{l \rightarrow j}] \pi(l) + 2\mathbb{E}[T_{j \rightarrow n}]^2 - \mathbb{E}[T_{j \rightarrow n}] \\ &\leq 2\mathbb{E}[T_{b \rightarrow j}] \sum_{k=j}^{n-1} \frac{\pi(\llbracket b, k \rrbracket)}{p_k \pi(k)} + 2\mathbb{E}[T_{j \rightarrow n}]^2 - \mathbb{E}[T_{j \rightarrow n}] \\ &= 2\mathbb{E}[T_{b \rightarrow j}] \mathbb{E}[T_{j \rightarrow n}] + 2\mathbb{E}[T_{j \rightarrow n}]^2 - \mathbb{E}[T_{j \rightarrow n}]. \end{aligned} \tag{4.43}$$

□

5 Cut-off and Escape for Half-well Models

We shall proof parts 2 and 3 of Theorem 1 in two stages. In this section we consider the half-well models, obtained when setting $b = 0$ and $q_0 = 0$ or $a = 0$ and $p_0 = 0$. The actual result is a little stronger than the statement of Theorem 1. It is based on the quantities

$$Q^{(a)}(x) := \frac{1}{\pi^{(a)}(\llbracket x, a \rrbracket)} \sum_{c \in \llbracket x, a \rrbracket} \frac{\pi^{(a)}(\llbracket c, a \rrbracket)^2}{q_c \pi^{(a)}(c)}; \quad Q^{(a)} := \sup_{x \in \llbracket 0, a \rrbracket} Q^{(a)}(x). \tag{5.1}$$

As

$$\pi^{(a)}(\llbracket 1, a \rrbracket) Q^{(a)}(1) \leq Q^{(a)}(1) \leq Q^{(a)} \leq K_a^2 K_q, \tag{5.2}$$

the following lemma implies parts 2 and 3 of Theorem 1.

Lemma 4 *Let $X^{(a)}$ be a family of irreducible birth-and-death chains on $\llbracket 0, a \rrbracket$.*

(i) *If*

$$\pi^{(a)}(\llbracket 1, a \rrbracket) \frac{Q^{(a)}(1)}{\mathbb{E}[T_{a \rightarrow 0}^{(a)}]} \xrightarrow{a \rightarrow \infty} 0, \tag{5.3}$$

then $\mathbb{E}[T_{a \rightarrow 0}^{(a)}] \ll_{\text{ms}} \mathbb{E}[T_{0 \rightarrow a}^{(a)}]$ and, as a consequence, the random variables $T_{0 \rightarrow a}^{(a)}$ have escape-time behavior at mean times.

(ii) *If*

$$\frac{Q^{(a)}}{\mathbb{E}[T_{a \rightarrow 0}^{(a)}]} \xrightarrow{a \rightarrow \infty} 0, \tag{5.4}$$

then $\text{Var}(T_{a \rightarrow 0}^{(a)} / \mathbb{E}[T_{a \rightarrow 0}^{(a)}]) \rightarrow 0$ as $a \rightarrow \infty$ and, as a consequence, the random variables $T_{a \rightarrow 0}^{(a)}$ have cut-off behavior at mean times.

Proof (i) We have to verify that both conditions in Definition 3 are valid for $\ell = 0, \mathcal{H}_a = \{a\}$; escape behavior follows then from Theorem 2. The second condition is a consequence of (4.42) which for the half well implies that

$$\mathbb{E}[(T_{0 \rightarrow a}^{(a)})^2] \leq 2\mathbb{E}[T_{0 \rightarrow a}^{(a)}]^2. \tag{5.5}$$

Therefore the sequence $S^{(a)} = T_{0 \rightarrow a}^{(a)} / \mathbb{E}[T_{0 \rightarrow a}^{(a)}]$ is uniformly square integrable and thus, by Schwartz inequality, uniformly integrable.

The first condition amounts to proving that $\mathbb{E}[T_{a \rightarrow 0}^{(a)}] / \mathbb{E}[T_{0 \rightarrow a}^{(a)}] \rightarrow 0$ as $a \rightarrow \infty$ or, equivalently, that

$$\frac{\mathbb{E}[T_{a \rightarrow 0}^{(a)}]}{\mathbb{E}[T_{a \rightarrow 0}^{(a)}] + \mathbb{E}[T_{0 \rightarrow a}^{(a)}]} \xrightarrow{a \rightarrow \infty} 0. \tag{5.6}$$

By (4.3) and (4.7) this corresponds to

$$\Gamma^{(a)} := \frac{\sum_{x=1}^a \frac{\pi^{(a)}(\llbracket x, a \rrbracket)}{q_x \pi^{(a)}(x)}}{\sum_{x=1}^a \frac{1}{q_x \pi^{(a)}(x)}} \xrightarrow{a \rightarrow \infty} 0. \tag{5.7}$$

To prove this we consider the probability measure on $\llbracket 0, a \rrbracket$ defined by expectations

$$\mathcal{E}(F) := \frac{\sum_{x=1}^a \frac{F(x)}{q_x \pi^{(a)}(x)}}{\sum_{x=1}^a \frac{1}{q_x \pi^{(a)}(x)}}. \tag{5.8}$$

Indeed, the inequality $\mathcal{E}(F)^2 \leq \mathcal{E}(F^2)$ for $F(x) = \pi^{(a)}(\llbracket x, a \rrbracket)$ implies that

$$\Gamma^{(a)} \leq \frac{\sum_{x=1}^a \frac{\pi^{(a)}(\llbracket x, a \rrbracket)^2}{q_x \pi^{(a)}(x)}}{\sum_{x=1}^a \frac{\pi^{(a)}(\llbracket x, a \rrbracket)}{q_x \pi^{(a)}(x)}} = \frac{\sum_{x=1}^a \frac{\pi^{(a)}(\llbracket x, a \rrbracket)^2}{q_x \pi^{(a)}(x)}}{\mathbb{E}[T_{a \rightarrow 0}^{(a)}]}. \tag{5.9}$$

Thus,

$$\Gamma^{(a)} \leq \pi^{(a)}(\llbracket 1, a \rrbracket) \frac{Q^{(a)}(1)}{\mathbb{E}[T_{a \rightarrow 0}^{(a)}]}, \tag{5.10}$$

and (5.7) is a consequence of hypothesis (5.3).

(ii) Due to the independence of the hitting times and to (4.41),

$$\text{Var}(T_{a \rightarrow 0}^{(a)}) = \sum_{x=1}^a \text{Var}(T_{x \rightarrow x-1}^{(a)}) \leq \sum_{x=1}^a \frac{2}{q_x \pi(x)} \sum_{c=x}^a \frac{\pi(\llbracket c, a \rrbracket)^2}{q_c \pi(c)}. \tag{5.11}$$

Hence, by (4.3),

$$\text{Var}\left(\frac{T_{a \rightarrow 0}^{(a)}}{\mathbb{E}[T_{a \rightarrow 0}^{(a)}]}\right) \leq \frac{2Q^{(a)}}{\mathbb{E}[T_{a \rightarrow 0}^{(a)}]} \xrightarrow{a \rightarrow \infty} 0. \tag{5.12}$$

The cut-off behavior is, thus, a consequence of Proposition 1. □

6 Cut-off and Escape Behavior for the Full Well

6.1 Comparison (In)equalities

Part of the results will be obtained by comparison with the half-well hitting times. Let us therefore define, for each process $X^{(a)}$, its left $\check{X}^{(a)}$ and right $\hat{X}^{(a)}$ half-well versions. The latter is a birth-and-death process on $\llbracket 0, a \rrbracket$ with transition rates $(\hat{p}_x, \hat{q}_x, \hat{r}_x) = (p_x, q_x, r_x)$ for $1 \leq x \leq a$ and $(\hat{p}_0, \hat{q}_0, \hat{r}_0) = (p_0, 0, q_0 + r_0)$. Likewise, $\check{X}^{(a)}$ is a process on $\llbracket b, 0 \rrbracket$ with transition rates $(\check{p}_x, \check{q}_x, \check{r}_x) = (p_x, q_x, r_x)$ for $b \leq x \leq -1$ and $(\check{p}_0, \check{q}_0, \check{r}_0) = (0, q_0, p_0 + r_0)$. From (2.3) we see that the left or right invariant measure differ from the bilateral one only in a normalization constant:

$$\frac{\pi^{(a)}(x)}{\pi^{(a)}(y)} = \begin{cases} \frac{\check{\pi}^{(a)}(x)}{\check{\pi}^{(a)}(y)}, & x \in \llbracket b, 0 \rrbracket, \\ \frac{\hat{\pi}^{(a)}(x)}{\hat{\pi}^{(a)}(y)}, & x \in \llbracket 0, a \rrbracket. \end{cases} \tag{6.1}$$

The behavior for the full well is proven on the basis of the following comparison inequalities.

Proposition 3 *Let $X^{(a)}$ be a birth-and-death process and $\check{X}^{(a)}, \hat{X}^{(a)}$ its left and right half-well versions. Then,*

$$\mathbb{E}[T_{a \rightarrow 0}^{(a)}] = \mathbb{E}[\hat{T}_{a \rightarrow 0}^{(a)}], \quad \text{Var}\left(\frac{T_{a \rightarrow 0}^{(a)}}{\mathbb{E}[T_{a \rightarrow 0}^{(a)}]}\right) = \text{Var}\left(\frac{\hat{T}_{a \rightarrow 0}^{(a)}}{\mathbb{E}[\hat{T}_{a \rightarrow 0}^{(a)}]}\right), \tag{6.2}$$

$$\mathbb{E}[T_{b \rightarrow 0}^{(a)}] = \mathbb{E}[\check{T}_{b \rightarrow 0}^{(a)}], \quad \text{Var}\left(\frac{T_{b \rightarrow 0}^{(a)}}{\mathbb{E}[T_{b \rightarrow 0}^{(a)}]}\right) = \text{Var}\left(\frac{\check{T}_{b \rightarrow 0}^{(a)}}{\mathbb{E}[\check{T}_{b \rightarrow 0}^{(a)}]}\right), \tag{6.3}$$

and

$$\mathbb{E}[T_{0 \rightarrow a}^{(a)}] = \frac{\pi^{(a)}(\llbracket b, -1 \rrbracket)\mathbb{E}[\hat{T}_{a \rightarrow 0}^{(a)}] + \mathbb{E}[\hat{T}_{0 \rightarrow a}^{(a)}]}{\pi^{(a)}(\llbracket 0, a \rrbracket)} \geq \mathbb{E}[\hat{T}_{0 \rightarrow a}^{(a)}], \tag{6.4}$$

$$\mathbb{E}[T_{0 \rightarrow b}^{(a)}] = \frac{\pi^{(a)}(\llbracket 1, a \rrbracket)\mathbb{E}[\check{T}_{b \rightarrow 0}^{(a)}] + \mathbb{E}[\check{T}_{0 \rightarrow b}^{(a)}]}{\pi^{(a)}(\llbracket b, 0 \rrbracket)} \geq \mathbb{E}[\check{T}_{0 \rightarrow b}^{(a)}]. \tag{6.5}$$

Furthermore, if

$$C_a := \frac{\mathbb{E}[T_{a \rightarrow 0}^{(a)}]}{\mathbb{E}[T_{0 \rightarrow a}^{(a)}]} \vee \frac{\mathbb{E}[T_{b \rightarrow 0}^{(a)}]}{\mathbb{E}[T_{0 \rightarrow b}^{(a)}]} \leq 1, \tag{6.6}$$

then

$$\frac{(1 - 2C_a)}{2} \mathbb{E}[T_{0 \rightarrow a}^{(a)}] \wedge \mathbb{E}[T_{0 \rightarrow b}^{(a)}] \leq \mathbb{E}[T_{0 \rightarrow \{a,b\}}^{(a)}] \leq \mathbb{E}[T_{0 \rightarrow a}^{(a)}] \wedge \mathbb{E}[T_{0 \rightarrow b}^{(a)}]. \tag{6.7}$$

Proof The identities in (6.2) and (6.3) are an immediate consequence of (4.3)–(4.6) and (6.1).

Proof of (6.4) and (6.5) From (4.5), (4.7) and (6.2),

$$\begin{aligned} \mathbb{E}[T_{0 \rightarrow a}^{(a)}] &= \sum_{k=0}^{a-1} \frac{\pi(\llbracket b, k \rrbracket)}{p_k \pi(k)} = \sum_{k=0}^{a-1} [\pi(\llbracket b, -1 \rrbracket) + \pi(\llbracket 0, k \rrbracket)] \frac{1}{p_k \pi(k)} \\ &= \pi(\llbracket b, -1 \rrbracket) \sum_{k=0}^{a-1} \frac{1}{p_k \pi(k)} + \mathbb{E}[\hat{T}_{0 \rightarrow a}^{(a)}] \\ &= \pi(\llbracket b, -1 \rrbracket)(\mathbb{E}[T_{a \rightarrow 0}^{(a)}] + \mathbb{E}[T_{0 \rightarrow a}^{(a)}]) + \mathbb{E}[\hat{T}_{0 \rightarrow a}^{(a)}]. \end{aligned} \tag{6.8}$$

Passing $\pi(\llbracket b, -1 \rrbracket)\mathbb{E}[T_{0 \rightarrow a}^{(a)}]$ to the left-hand side we arrive to (6.4). The proof of (6.5) is analogous.

Proof of (6.7) The upper bound is an immediate consequence of the fact that $T_{0 \rightarrow \{a,b\}}^{(a)} \leq T_{0 \rightarrow a}^{(a)}, T_{0 \rightarrow b}^{(a)}$. For the lower bound we observe that from (4.8),

$$\mathbb{E}[T_{0 \rightarrow \{a,b\}}^{(a)}] = \mathbb{E}[T_{0 \rightarrow a}^{(a)}] \frac{\mathbb{E}[T_{a \rightarrow b}^{(a)}]}{\mathbb{E}[T_{b \rightarrow a}^{(a)}] + \mathbb{E}[T_{a \rightarrow b}^{(a)}]} - \mathbb{E}[T_{a \rightarrow 0}^{(a)}] \frac{\mathbb{E}[T_{b \rightarrow a}^{(a)}]}{\mathbb{E}[T_{b \rightarrow a}^{(a)}] + \mathbb{E}[T_{a \rightarrow b}^{(a)}]}. \tag{6.9}$$

Hence, if $\lambda_a := \mathbb{E}[T_{a \rightarrow b}^{(a)}]/[\mathbb{E}[T_{b \rightarrow a}^{(a)}] + \mathbb{E}[T_{a \rightarrow b}^{(a)}]]$,

$$\mathbb{E}[T_{0 \rightarrow \{a,b\}}^{(a)}] \geq \mathbb{E}[T_{0 \rightarrow a}^{(a)}][\lambda_a - C_a] \geq \mathbb{E}[T_{0 \rightarrow a}^{(a)}] \wedge \mathbb{E}[T_{0 \rightarrow b}^{(a)}][\lambda_a - C_a]. \tag{6.10}$$

Analogously, using (4.9) we obtain

$$\mathbb{E}[T_{0 \rightarrow \{a,b\}}^{(a)}] \geq \mathbb{E}[T_{0 \rightarrow a}^{(a)}] \wedge \mathbb{E}[T_{0 \rightarrow b}^{(a)}][1 - \lambda_a] - C_a. \tag{6.11}$$

Adding (6.10) to (6.11) we obtain the lower bound in (6.7). □

6.2 Proof of Cut-off and Escape Behavior for the Full Well

In this section the notation “ $o(1)$ ” stands for a positive term that goes to zero as a goes to infinity.

6.2.1 Cut-off Behavior of $T_{a \rightarrow 0}^{(a)}$ and $T_{b \rightarrow 0}^{(a)}$

The laws of these hitting times depend only on half-well trajectories, therefore their cut-off behavior follows from in Sect. 5.

More formally, let us prove the cut-off behavior of $T_{a \rightarrow 0}^{(a)}$, the proof for $T_{b \rightarrow 0}^{(a)}$ is analogous.

We suppose that $X^{(a)}$ has a strong drift to the left (0^+ -SD). We thus have $K_a^2 / \mathbb{E}[T_{a \rightarrow 0}^{(a)}] \xrightarrow{a \rightarrow \infty} 0$.

As a consequence of (6.1) the quantities K_a and $Q^{(a)}$ do not depend on the left part of the well (that is: $\hat{K}_a = K_a$ and $\hat{Q}^{(a)} = Q^{(a)}$). Thus, by (6.2) and since $Q^{(a)} \leq K_a^2 K_q$ (see (5.2)), we can apply part (ii) of Lemma 4 to the half-well version $\hat{X}^{(a)}$, to conclude that $\text{Var}(T_{a \rightarrow 0}^{(a)} / \mathbb{E}[T_{a \rightarrow 0}^{(a)}]) \rightarrow 0$ as $a \rightarrow \infty$. Cut-off follows from Proposition 1.

6.2.2 Escape Behavior of $T_{0 \rightarrow a}^{(a)}$ and $T_{0 \rightarrow b}^{(a)}$

We consider $T_{0 \rightarrow a}^{(a)}$, the proof for $T_{0 \rightarrow b}^{(a)}$ is analogous. We apply Theorem 2 by proving the validity of conditions 1 and 2 of Definition 3 for $\ell = 0$ and $\mathcal{H}_a = \{a\}$. Condition 1 requires that

$$\frac{\mathbb{E}[T_{a \rightarrow 0}^{(a)}]}{\mathbb{E}[T_{0 \rightarrow a}^{(a)}]} \vee \frac{\mathbb{E}[T_{b \rightarrow 0}^{(a)}]}{\mathbb{E}[T_{0 \rightarrow a}^{(a)}]} \xrightarrow{a \rightarrow \infty} 0. \tag{6.12}$$

But the left identity in (6.2) and the inequality in (6.4) imply that

$$\frac{\mathbb{E}[T_{a \rightarrow 0}^{(a)}]}{\mathbb{E}[T_{0 \rightarrow a}^{(a)}]} = \frac{\mathbb{E}[\hat{T}_{a \rightarrow 0}^{(a)}]}{\mathbb{E}[T_{0 \rightarrow a}^{(a)}]} \leq \frac{\mathbb{E}[\hat{T}_{a \rightarrow 0}^{(a)}]}{\mathbb{E}[\hat{T}_{0 \rightarrow a}^{(a)}]} \tag{6.13}$$

which tends to zero as a diverges because of part (i) of Lemma 4 (using again (6.1) and (5.2) as in the previous proof). On the other hand, the leftmost hypothesis in (2.17) guarantees that $\mathbb{E}[T_{b \rightarrow 0}^{(a)}] / \mathbb{E}[T_{0 \rightarrow a}^{(a)}]$ tends to 0 as a goes to infinity. This proves (6.12). Condition 2 follows from (4.42) which implies that

$$\frac{\mathbb{E}[(T_{0 \rightarrow a}^{(a)})^2]}{\mathbb{E}[T_{0 \rightarrow a}^{(a)}]^2} \leq 2 + 2 \frac{\mathbb{E}[T_{b \rightarrow 0}^{(a)}]}{\mathbb{E}[T_{0 \rightarrow a}^{(a)}]} = 2 + o(1). \tag{6.14}$$

The second line is, again, due to the leftmost hypothesis in (2.17). This proves that the sequence $T_{0 \rightarrow a}^{(a)} / \mathbb{E}[T_{0 \rightarrow a}^{(a)}]$ is uniformly square integrable and therefore uniformly integrable.

6.2.3 Escape Behavior of $T_{0 \rightarrow \{a,b\}}^{(a)}$

We verify conditions 1 and 2 of Definition 3 for $\ell = 0$ and $\mathcal{H}_a = \{a, b\}$. For the former we must consider the ratio

$$R^{(a)} := \frac{\mathbb{E}[T_{a \rightarrow 0}^{(a)}] \vee \mathbb{E}[T_{b \rightarrow 0}^{(a)}]}{\mathbb{E}[T_{0 \rightarrow \{a,b\}}^{(a)}]} \tag{6.15}$$

By the lower bound in (6.7),

$$R^{(a)} \leq \frac{2}{1 - 2C_a} \frac{\mathbb{E}[T_{a \rightarrow 0}^{(a)}] \vee \mathbb{E}[T_{b \rightarrow 0}^{(a)}]}{\mathbb{E}[T_{0 \rightarrow a}^{(a)}] \wedge \mathbb{E}[T_{0 \rightarrow b}^{(a)}]} \tag{6.16}$$

As seen in (6.13): $\mathbb{E}[T_{a \rightarrow 0}^{(a)}] / \mathbb{E}[T_{0 \rightarrow a}^{(a)}] \leq \mathbb{E}[\hat{T}_{a \rightarrow 0}^{(a)}] / \mathbb{E}[\hat{T}_{0 \rightarrow a}^{(a)}]$ which tends to zero by part (i) of Lemma 4. Analogously, using the left identity in (6.3) and the inequality in (6.5), we get that $\mathbb{E}[T_{b \rightarrow 0}^{(a)}] / \mathbb{E}[T_{0 \rightarrow b}^{(a)}]$ tends to zero, and as a consequence C_a also tends to zero as $a \rightarrow \infty$.

Condition 1 is proven, since by hypothesis (2.17) $\mathbb{E}[T_{a \rightarrow 0}^{(a)}] / \mathbb{E}[T_{0 \rightarrow b}^{(a)}]$ and $\mathbb{E}[T_{b \rightarrow 0}^{(a)}] / \mathbb{E}[T_{0 \rightarrow a}^{(a)}]$ tend to zero.

To prove condition 2, we use the fact that $(T_{0 \rightarrow \{a,b\}}^{(a)})^2 \leq (T_{0 \rightarrow a}^{(a)})^2, (T_{0 \rightarrow b}^{(a)})^2$ and the lower bound in (6.7) to obtain

$$\begin{aligned} \frac{\mathbb{E}[(T_{0 \rightarrow \{a,b\}}^{(a)})^2]}{\mathbb{E}[T_{0 \rightarrow \{a,b\}}^{(a)}]^2} &\leq \left(\frac{2}{1 - 2C_a} \right)^2 \frac{\mathbb{E}[(T_{0 \rightarrow a}^{(a)})^2] \wedge \mathbb{E}[(T_{0 \rightarrow b}^{(a)})^2]}{\mathbb{E}[T_{0 \rightarrow a}^{(a)}]^2 \wedge \mathbb{E}[T_{0 \rightarrow b}^{(a)}]^2} \\ &\leq \left(\frac{2}{1 - 2C_a} \right)^2 \frac{\mathbb{E}[(T_{0 \rightarrow a}^{(a)})^2]}{\mathbb{E}[T_{0 \rightarrow a}^{(a)}]^2} \vee \frac{\mathbb{E}[(T_{0 \rightarrow b}^{(a)})^2]}{\mathbb{E}[T_{0 \rightarrow b}^{(a)}]^2} \\ &\leq \left(\frac{2}{1 - o(1)} \right)^2 [2 + o(1)], \end{aligned} \tag{6.17}$$

where the last line is due to (6.14) and its analogous for $a \leftrightarrow b$. This proves the uniform square integrability—and, in consequence, the uniform integrability—of the sequence $T_{0 \rightarrow \{a,b\}}^{(a)} / \mathbb{E}[T_{0 \rightarrow \{a,b\}}^{(a)}]$.

Remark 1 The same argument used in (6.13) show that the conditions

$$\frac{\mathbb{E}[\check{T}_{b \rightarrow 0}^{(a)}]}{\mathbb{E}[\hat{T}_{0 \rightarrow a}^{(a)}]} \xrightarrow{a \rightarrow \infty} 0, \quad \frac{\mathbb{E}[\hat{T}_{a \rightarrow 0}^{(a)}]}{\mathbb{E}[\check{T}_{0 \rightarrow b}^{(a)}]} \xrightarrow{a \rightarrow \infty} 0 \tag{6.18}$$

are sufficient for the validity of (2.17). This requirement is weaker than (2.18).

7 Proof of Part 1 of Theorem 1: Equality of the Laws of Direct and Reverse Trajectories

This property is a direct consequence of the reversibility of the invariant measure, and is unrelated to the particular behavior of hitting times. While we do not doubt that the result is well known, we have not found it spelled out in the literature. For completeness we are presenting a detailed proof. The property stated in Theorem 1 is a particular instance of the following proposition.

Proposition 4 *Let us consider a recurrent Markov process on a finite alphabet \mathcal{A} defined by transition probabilities $p(x, y)$ with invariant reversible measure π . Then, for any $x, y \in \mathcal{A}$ with $\pi(x), \pi(y) \neq 0$, and any natural number k ,*

$$\mathbb{P}(\tilde{T}_{x \rightarrow y} = k) = \mathbb{P}(\tilde{T}_{y \rightarrow x} = k), \tag{7.1}$$

where $\tilde{T}_{x \rightarrow y}$ is the time needed to hit y after hitting x (defined in Sect. 2.4).

Proof It is decomposed in two claims, the first of which is adapted from [50]. Let $v^k = (v_1, \dots, v_k)$ denote a trajectory of length k , let $\mathcal{V}_{x \rightarrow y}^k$ denote the set of all trajectories of length k “strictly between x and y ” and let $\mathcal{U}_{x \rightarrow y}$ be the set of all finite such trajectories:

$$\mathcal{V}_{x \rightarrow y}^k := \{v^k : v_1 = x; v_k = y; v_i \neq x, y, 1 < i < k\}, \quad \mathcal{U}_{x \rightarrow y} := \bigcup_{k < \infty} \mathcal{V}_{x \rightarrow y}^k. \tag{7.2}$$

Let X_z denote the Markov process started at $z \in \mathcal{A}$. Following [50], we say that X_z starts as v^k if for all $i = 1, \dots, k$, $X_z(i - 1) = v_i$, and for a set $\mathcal{V} \subset \mathcal{A}$, that X_z starts in \mathcal{V} if X_z starts as v^k for some $v^k \in \mathcal{V}$. Let \mathcal{R} denote the time-reversal operator on the space of finite trajectories: $\mathcal{R}(v^k) = (v_k, \dots, v_1)$.

Claim 1:

$$\begin{aligned} &\mathbb{P}(X_x \text{ starts in } \mathcal{V}_{x \rightarrow y}^k \mid X_x \text{ starts in } \mathcal{U}_{x \rightarrow y}) \\ &= \mathbb{P}(X_y \text{ starts in } \mathcal{R}(\mathcal{V}_{x \rightarrow y}^k) \mid X_y \text{ starts in } \mathcal{R}(\mathcal{U}_{x \rightarrow y})). \end{aligned} \tag{7.3}$$

Indeed, by reversibility,

$$\begin{aligned} \pi(x)\mathbb{P}(X_x \text{ starts as } v^k) &= \pi(x)p(x, v_2)p(v_2, v_3) \cdots p(v_{k-2}, v_{k-1})p(v_{k-1}, y) \\ &= p(v_2, x)p(v_3, v_2) \cdots p(v_{k-1}, v_{k-2})p(y, v_{k-1})\pi(y) \\ &= \pi(y)\mathbb{P}(X_y \text{ starts as } \mathcal{R}(v^k)). \end{aligned} \tag{7.4}$$

Summing over $v^k \in \mathcal{V}_{x \rightarrow y}^k$, we get $\pi(x)\mathbb{P}(X_x \text{ starts in } \mathcal{V}_{x \rightarrow y}^k) = \pi(y)\mathbb{P}(X_y \text{ starts as } \mathcal{R}(\mathcal{V}_{x \rightarrow y}^k))$ and thus, summing over k ,

$$\pi(x)\mathbb{P}(X_x \text{ starts in } \mathcal{U}_{x \rightarrow y}) = \pi(y)\mathbb{P}(X_y \text{ starts in } \mathcal{R}(\mathcal{U}_{x \rightarrow y})). \tag{7.5}$$

Dividing each side of (7.4) by the corresponding side of (7.5) we arrive to (7.3).

Claim 2:

$$\mathbb{P}(\tilde{T}_{x \rightarrow y} = k) = \mathbb{P}(X_x \text{ starts in } \mathcal{V}_{x \rightarrow y}^k \mid X_x \text{ starts in } \mathcal{U}_{x \rightarrow y}), \tag{7.6}$$

$$\mathbb{P}(\tilde{T}_{y \rightarrow x} = k) = \mathbb{P}(X_y \text{ starts in } \mathcal{R}(\mathcal{V}_{x \rightarrow y}^k) \mid X_y \text{ starts in } \mathcal{R}(\mathcal{U}_{x \rightarrow y})). \tag{7.7}$$

Let $\tau_x := \tau_{x \rightarrow x, y}^{(x)}$ be the time of last visit to x before hitting y , and for $n \in \mathbb{N}$ let us denote $\theta_n : \mathbb{N} \rightarrow \mathbb{N}$ the “forward time-translation” $\theta_n(t) = t + n$. Partitioning over all possible values of τ_x and using the Markov property we obtain

$$\begin{aligned}
 \mathbb{P}(\tilde{T}_{x \rightarrow y} = k) &= \sum_n \mathbb{P}(\tau_x = n; X_x \circ \theta_n \text{ starts in } \mathcal{V}_{x \rightarrow y}^k) \\
 &= \sum_n \mathbb{P}(X_x(t) \neq 0, t < n; X_x(n) = x; X_x \circ \theta_n \text{ starts in } \mathcal{V}_{x \rightarrow y}^k) \\
 &= \mathbb{P}(X_x \text{ starts in } \mathcal{V}_{x \rightarrow y}^k) \sum_n \mathbb{P}(X_x(t) \neq 0, t < n; X_x(n) = a). \tag{7.8}
 \end{aligned}$$

Summing over k , we get

$$1 = \sum_n \mathbb{P}(X_x(t) \neq 0, t < n; X_x(n) = a) \sum_k \mathbb{P}(X_x \text{ starts in } \mathcal{V}_{x \rightarrow y}^k); \tag{7.9}$$

therefore

$$\sum_n \mathbb{P}(X_x(t) \neq 0, t < n; X_x(n) = a) = \frac{1}{\mathbb{P}(X_x \text{ starts in } \mathcal{U}_{x \rightarrow y})}. \tag{7.10}$$

The combination of (7.8) and (7.10) yields (7.6). The proof of (7.7) is analogous. □

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