# TUTORIAL III: One-parameter bifurcation analysis of limit cycles with MATCONT

Yu.A. Kuznetsov Department of Mathematics Utrecht University Budapestlaan 6 3508 TA, Utrecht

N. Neirynck Department of Applied Mathematics, Computer Science and Statistics Ghent University Krijgslaan 281, S9 B-9000, Ghent

October 26, 2020

This session was tested on MATCONT7.0 with MATLAB2018b. It is devoted to the numerical initialization and continuation of limit cycles in systems of autonomous ODEs depending on one parameter

$$\dot{x} = f(x, \alpha), \quad x \in \mathbb{R}^n, \alpha \in \mathbb{R},$$

and detection of their bifurcations. We will also show how to start the continuation of a limit cycle from the Hopf bifurcation and a doubled cycle from the period-doubling bifurcation.

### 1 Cycle initialization from a converging orbit

We consider again the *Rössler system* that was introduced in TUTORIAL I:

$$\begin{cases} \dot{x} = -y - z \\ \dot{y} = x + Ay \\ \dot{z} = Bx - Cz + xz, \end{cases}$$
(1)

where (x, y, z) are the phase variables, and (A, B, C) are the parameters.

Input system (1) in MATCONT, generating the derivatives of order 1, 2 and 3 symbolically. We start with computing by time integration an orbit, using the **Starter** and **Integrator** windows presented in Figure 1.

📣 Starter		- 🗆 ×	承 Integrator	
			Method	ode45 🔹
	Initial Point		Interval	500
+	initian i onit		EventFunction	<disabled></disabled>
, v			InitStepSize	<automatic></automatic>
Ĵ		->	MaxStepSize	<automatic></automatic>
y 7		5	RelTolerance	0.001
^		10	AbsTolerance	1e-06
		0.2	Refine	4
		0.4	Normcontrol	
C		4.5		

Figure 1: The **Starter** and **Integrator** windows for the initial time integration.

The computed orbit is presented in the 3D-plot in Figure 2 in (x, y, z) - space within the region

$$-9 \le x \le 9, -9 \le y \le 9, -2 \le z \le 11.$$

It is visually clear that the orbit has converged to a (presumably stable) limit cycle. We select the last point of the orbit using **Select**|**Initial Point**|**Last Point**|**Select Point** and clear the **Plot3D** window.

It is readily seen that time integration from the selected point over a time interval 5 does not close the orbit, see the **Starter** and **Integrator** windows in Figure 3, and the orbit displayed in Figure 4.

Now perform a time integration over an interval 8 and check that it closes the limit cycle. This implies that 8 is larger than the period of the limit cycle but smaller than twice that period, which is the condition for starting the continuation of limit cycles from an orbit that is computed along the limit cycle. That is why time integrations over an interval 5 or 500 are of no use.



Figure 2: 3D-plot of the computed orbit.

Initial Point     Method       t     500       x     4.42233710505349       y     -1.58553069272306   RefTolerance	ode45 💌
Z         1.10885496225373         AbsTolerance           A         0.2         Refine           B         0.4         Normcontrol           C         4.5         Normcontrol	<disabled> <automatic> <automatic> 0.001 1e-06 4</automatic></automatic></disabled>

Figure 3: **Starter** and **Integrator** windows for time integration from a selected point on the orbit.



Figure 4: Computed orbit over an interval 5.

Now press **Control**|**View Result** and double-click at **Select Cycle** (we note that a singleclick at **Select Cycle** followed by clicking **Select Point** also works). This opens a small **Choose tolerance** ... input window with two input fields. The top one allows to change the tolerance for detecting a limit cycle along the orbit. The bottom one allows to change the number of mesh intervals that will be used to discretize the limit cycle. Make sure that it is set to 40; the window should now look like Figure 5.

Now press **OK**. The main MATCONT window is then prepared for the continuation of a limit cycle, see Figure 6(left). In the corresponding **Starter** window activate the parameter **A** and the **Period**. Also, check all singularity monitoring boxes as in Figure 6(right). We note that the initial value of the **Period** is estimated by the initializer and equal to 6.27..., indeed a value between 5 and 8.

🛃 Choose tolerance 💶 🗙		
Enter the tolerance to select a cycle		
1e-2		
Enter the number of test intervals		
40		
OK Cancel		
Calicer		

Figure 5: Input window opened by pressing the **Select Cycle** button.

In the corresponding **Continuer** window only default values are to be used. Open a **Numeric** window and check **Multipliers** in its **Layout** menu for the multipliers of the periodic orbits to be displayed in the **Numeric** window during continuation.

Press Compute Forward. The continuation of limit cycles now starts. Observe that there is

承 Matcont GU	I DEMO				- U ×	承 Starter	
Select Type \	Window/Output	Compute	Options	Help	ъ		
						ΘA	0.2
Class	ODE					СВ	0.4
						C C	4.5
						Period	6.2759426320367
Current System						Discretizati	on Data
System	Ross					ntst	40
						ncol	4
						Monitor Sing	ularities
Derivatives	SSSNN					Branch Point of Cycles (BPC)	<b>N</b>
						Period Doubling (flip) bifurcatio	n (PD) 🔽
Current Curve						Limit Point bifurcation of cycles	s (LPC)
Name	<nothing></nothing>					Neimark-Sacker (torus) bifurca	ution (NS)
Disgram	disoram					Calculate m	ultipliers
Diagram	ulayram					multipliers	च
Initial Point Type	LC from O	rbit (LC)				Phase Respor	nse Curve
Curve Type	Limit cycle	e (LC)				Input	1
						PRC	Onen PBC Plot
Initializer	Limit cycle	e (init_LC_I	.C)		•	dPRC	Open dPBC Plot
	, ,						open di Ro Flot

Figure 6: The main MATCONT window when prepared to start the continuation of limit cycles.

period-doubling bifurcation for A = 0.27191773. The **Plot3D** window and the **Numeric** window are displayed in Figures 7. Observe that at the PD-point there is a multiplier equal to -1 (i.e., absolute value 1 and argument equal to  $180^{\circ}$ ).

In the MATLAB command line the output

```
Period Doubling (period = 6.148967e+00, parameter = 2.719177e-01)
Normal form coefficient = -4.283828e-03
```

is generated, including the normal form coefficient of the  $\mathsf{PD}$  bifurcation.

Stop the computation and end the session by closing all output windows.



Figure 7: The **Plot3D** and the **Numeric** windows at the period-doubling bifurcation.

## 2 Fold and Neimark-Sacker bifurcations of cycles in a chemical model

Consider the following chemical model by *Steinmetz and Larter*:

$$\begin{cases}
\dot{A} = -k_1 ABX - k_3 ABY + k_7 - k_{-7}A, \\
\dot{B} = -k_1 ABX - k_3 ABY + k_8, \\
\dot{X} = k_1 ABX - 2k_2 X^2 + 2k_3 ABY - k_4 X + k_6, \\
\dot{Y} = -k_3 ABY + 2k_2 X^2 - k_5 Y.
\end{cases}$$
(2)

We will fix all parameters but  $k_7$  and study periodic solutions (limit cycles) of (2) when this parameter varies.

#### 2.1 System specification

Specify a new ODE system – say StLar – in MATCONT

```
A'=-k1*A*B*X-k3*A*B*Y+k7-km7*A
B'=-k1*A*B*X-k3*A*B*Y+k8
X'=k1*A*B*X-2*k2*X^2+2*k3*A*B*Y-k4*X+k6
Y'=-k3*A*B*Y+2*k2*X^2-k5*Y
```

where (A,B,X,Y) are the coordinates and (k1,k2,k3,k4,k5,k6,k7,km7,k8) are the parameters. Use (default) t for time and generate symbolical derivatives of order 1, 2 and 3.

#### 2.2 Fold bifurcation of limit cycles

#### 2.2.1 Continuation of an equilibrium

We will continue an equilibrium of (2) and detect its Hopf bifurcation, from which the continuation of a limit cycle can be started.

Input **Type**|**Initial point**|**Equilibrium** and **Type**|**Curve**|**Equilibrium** in the main MAT-CONT window.

Input the following numerical data in the appeared **Starter** window:

A	31.78997
В	1.45468
Х	0.01524586
Y	0.1776113
k1	0.1631021
k2	1250
k3	0.046875
k4	20
k5	1.104
k6	0.001
k7	4.235322
km7	0.1175
k8	0.5

These values correspond to an unstable equilibrium (A, B, X, Y) in the system. Activate the parameter k7.

Open **Window/Output**|**Numeric** and change its appearance via the **Layout** menu. Namely, check **Eigenvalues** to be also shown in the window.

Use Window/Output|Graphic|2D plot to open the corresponding window and select the coordinates (A,B) as abscissa and ordinate, respectively, with the visibility limits:

Abscissa:	32	38
Ordinate:	0	4

respectively.

Start **Compute** |**Forward**. The equilibrium curve will be continued and you get a *Hopf bifurcation point* labeled by H. The message in the MATLAB Command Window

```
label = H , x = ( 34.808899 1.328517 0.015246 0.177611 4.590046 )
First Lyapunov coefficient = 1.527549e-02
```

at  $k_7 = 4.590046...$  indicates a *subcritical* Hopf bifurcation. Indeed, there are two eigenvalues of the equilibrium with Re  $\lambda_{1,2} \approx 0$  at this parameter value visible in the **Numeric** window. The critical frequency Im  $\lambda_1 \neq 0$ , while the first Lyapunov coefficient is positive. Thus, there should exist an unstable limit cycle, bifurcating from the equilibrium. Resume computations and terminate them when the curve leaves the graphic window.

For later use, rename the computed curve via **Select** |**Curve**|**Rename** into Equilibrium(+).

#### 2.2.2 Cycle continuation

Click **Select**|**Initial point**|**Hopf**|**Select Point** to select the H: Hopf point in the Equilibrium(+) curve as initial point. The **Starter** and **Continuer** windows for the continuation of the limit cycle from the Hopf point will appear.

Ensure that all boxes in the Monitor Singularities field of the Starter window are checked. Increase the MaxStepsize to 1.0 in the Continuer window to allow larger steps along the curve and set MaxNumPoints to 50. The Starter and Continuer windows should look like in Figure 8.

Change the layout of the **Numeric** window via **Numeric** |Layout by selecting all Multipliers to be shown. The absolute values (*modulae*) and arguments in *angular grads* will be displayed.

**Compute**|Forward will produce a family of cycles with a cycle limit point labeled by LPC at  $k_7 = 4.74838...$  The Numeric window corresponding to LPC is shown in Figure 9. Recall that exact numerical values could deviate slightly.

In the MATLAB Command Window, the following message appears:

```
Limit point cycle (period = 1.036108e+01, parameter = 4.748384e+00)
Normal form coefficient = -2.714838e-01
```

The critical cycle has (approximately) a double multiplier  $\mu = 1$  and the normal form coefficient is nonzero. Thus, the limit cycle manifold has a fold here. Resume the computations. The continuation algorithm will automatically follow the second (stable) cycle branch after the LPC point. Verify this by looking at the nontrivial multipliers in the **Numeric** window ( $|\mu| < 1$  for all such multipliers). The computations produce Figure 10.

To visualize LPC in another way, open another **Plot2D** window and select parameter k7 and **Period** of the cycle as abscissa and ordinate, respectively. Use the visibility limits:

Abscissa:	4.5	4.8
Ordinate:	7	12

After MatCont|Redraw Diagram in the Plot2D window, you will get a curve with a limit point, clearly indicating the presence of two limit cycles with different periods for  $k_7 < 4.74838$  near LPC (see Figure 11). Close both Plot2D windows.

#### 2.3 Neimark-Sacker bifurcation

#### 2.3.1 Backward continuation of the equilibrium

Load the first computed equilibrium curve Equilibrium(+) in the Data Browser window appearing after the Select|Curve command. Be sure to select Type|Curve|Equilibrium for continuation.



Figure 8: The Starter and Continuer windows for the cycle continuation.

📣 Numeric		
Layout		ъ.
	Parameters	
k7	4.74838428332547	
	Period	
Period	10.3610927822857	
	Multipliers	
Mod[1]	1.08189907163879e-12	
Mod[2]	0.295743662725967	
Mod[3]	0.999720145226892	
Mod[4]	1.00027505104632	
Arg[1]	0	
Arg[2]	0	
Arg[3]	0	
Arg[4]	0	

Figure 9: The Numeric window at the LPC-point.



Figure 10: The family of limit cycles bifurcating from the Hopf point  $\mathtt{H}:\mathsf{LPC}$  is a fold bifurcation of the cycle.



Figure 11: Period of the cycle versus  $k_7$ .

Open a new **Plot2D** window but select now B and X as abscissa and ordinate, respectively, with the visibility limits:

Abscissa:	25	27
Ordinate:	0	0.03

**Compute** |Backward and Extend several times until you get another *Hopf bifurcation* at  $k_7 = 0.712475...$  with the message

label = H , x = (  $1.808301 \ 25.573303 \ 0.015246 \ 0.177611 \ 0.712475$  ) First Lyapunov coefficient = -2.371880e-02

in the MATLAB Command Window. The first Lyapunov coefficient is negative now. This means that a *stable* limit cycle bifurcates from the equilibrium, when it loses stability. Resume computations and terminate them when the equilibrium curve leaves the graphic window. Rename the computed curve into Equilibrium(-).

#### 2.3.2 Cycle continuation

Select the Hopf point in the curve Equilibrium(-) as initial. MATCONT will prepare to continue a limit cycle curve from the Hopf point (curve type H\_LC). Check all boxes in the Monitor Singularities section of the Starter window. Activate k7 and the Period in the Starter window. Set

MaxStepsize	1
MaxNumPoints	25

in the **Continuer** window. Check Multipliers to be shown in the **Numeric** window.

Click **Compute**|Forward to start the continuation of the limit cycle. At  $k_7 = 0.716434...$  the message Neimark-Sacker indicates a *torus* bifurcation. In the MATLAB Command Window, the following message appears:

Neimark-Sacker (period = 1.091213e+01, parameter = 7.164336e-01) Normal form coefficient = -4.912065e-08.

Indeed, there are two complex multipliers with (approximately)  $|\mu| = 1$  and one trivial at  $\mu = 1$ . This can be seen in the **Numeric** window that stays open, see Figure 12. The normal form coefficient is small but nonzero, indicating that a stable two-dimensional *invariant torus* bifurcates from the limit cycle.

Resume computations further to see that after the NS-point the cycle becomes unstable (with two multipliers satisfying  $|\mu| > 1$ . You should get a family of limit cycles bifurcating from the Hopf point as in Figure 13.

Close the **Numeric** and all output windows.

#### 2.3.3 Dynamics on a stable torus

Click **Select**|**Initial point**... and select the NS: Neimark-Sacker point in the computed limit cycle curve. The critical parameter values will be read in from the archive. Immediately after that select **Type**|**Initial point**|**Point** and **Type**|**Curve**|**Orbit**. A point on the critical cycle will thus be selected as the initial for orbit integration.

Increase slightly the value of the parameter  $k_7$  and perturb the initial point by altering the value of B, namely set:

k7	0.7165
В	26.2

Change Method of integration to ode23s and alter



Figure 12: The **Numeric** window at the NS-point.



Figure 13: Family of limit cycles bifurcating from the second Hopf point.

Interval	1000
Rel.Toletance	1e-6
Abs.Tolerance	1e-9

in the **Integrator** window.

To speed up visualization, click **Options**|**Output Interval** and set it to 1000, see Figure 14





Clear the graphic window and **Compute**|**Forward** followed by **Compute**|**Extend**. The integration will take some time. After a transient, the orbit will exhibit modulated oscillations with two frequencies near the limit cycle. This is a motion on a stable two-dimensional torus born via the Neimark-Sacker bifurcation, see Figure 15. Open another **2Dplot** window with time **t** and



Figure 15: Dynamics on a stable 2-torus.

coordinate B as abscissa and ordinate, with the visibility limits:

Abscissa:	1000	2000
Ordinate:	25.0	26.5

After MatCont Redraw Curve, you will see the high-frequency oscillations with low-frequency modulation as in Figure 16.

Restore the original setting (i.e., 1) of **Options**|**Output Interval** via the main MATCONT window.



Figure 16: Modulated chemical oscillations.

## 3 Period-doubling bifurcation in an adaptive control model

Consider the following adaptive control system of Lur'e type

$$\begin{cases} \dot{x} = y, \\ \dot{y} = z, \\ \dot{z} = -\alpha z - \beta y - x + x^2. \end{cases}$$
(3)

We will fix  $\alpha = 1$  and continue limit cycles of (3) using  $\beta$  as a bifurcation parameter.

#### 3.1 System specification

As usual, define a new system in MATCONT with the coordinates x,y,z, parameters alpha,beta, and select derivatives of order 1, 2, and 3 to be generated symbolically.

#### 3.2 Equilibrium continuation

Select **Type**|**Initial point**|**Equilibrium** and **Type**|**Curve**|**Equilibrium**. In the **Starter** window, set **alpha** equal to 1 and activate **beta**.

Open a **Plot3D** window and select **beta,x** and **y** as variables along the coordinate axes with the visibility limits:

Abscissa:	0.4	1.2
Ordinate:	-0.5	1.2
Applicate:	-0.6	0.7

respectively.

 $\label{eq:compute} \begin{array}{c} \textbf{Compute} | \textbf{Forward} \ \text{results in an equilibrium curve with a Hopf bifurcation (labeled H) detected with the following message in the MATLAB Command Window: \end{array}$ 

label = H , x = ( 0.000000 0.000000 0.000000 1.000000 )
First Lyapunov coefficient = -3.000000e-01

The Hopf bifurcation occurs at  $\beta = 1$  and is supercritical, thus generating a stable limit cycle. Resume the continuation and eventually stop it, when the curve leaves the plotting region.

#### 3.3 Cycle continuation starting from the H-point

Click **Control**|**View Result** and double-click at the H: Hopf point. The **Starter** and **Continuer** windows appear, corresponding to the limit cycle curve H\_LC. Make sure that **beta** and **Period** are activated.

In the **Starter** window, use the number of mesh points ntst equal to 40 and check all boxes in the Monitor Singularities field. In the **Continuer** window, set MaxStepsize to 0.7 and MaxNumPoints to 80.

With **Window/Output**|**Numeric**, open a **Numeric** window and make the cycle **Multipliers** visible by checking them in the **Numeric**|**Layout** menu.

**Compute**|**Forward** will produce a branch of limit cycles of increasing amplitude with two *period-doubling bifurcations* (labeled PD). The **Numeric** windows at both PD bifurcations are shown in Figures 17 and 18.

🔺 Numeric		
Layout		Y
	Parameters	
beta	0.6273246340239	
	Period	
Period	8.38606719485977	
	Multipliers	
Mod[1]	0.000228022290534954	
Mod[2]	0.99999997339161	
Mod[3]	1.0000000000037	
Arg[1]	180	
Arg[2]	180	
Arg[3]	0	

Figure 17: The **Numeric** window at the first PD bifurcation. The bifurcation parameter value is  $\beta = 0.6273246...$ 

Resume the computations at both  $\mathtt{PD}$  points. The MATLAB Command Window will contain the messages

```
Period Doubling (period = 8.386068e+00, parameter = 6.273245e-01)
Normal form coefficient = -3.405330e-03
Period Doubling (period = 9.864971e+00, parameter = 5.417461e-01)
Normal form coefficient = -7.655596e-04
```

承 Numeric		
Layout		ы
	Parameters	
beta	0.541746134367183	
	Period	
Period	9.86497021716061	
	Multipliers	
Mod[1]	5.1963409062053e-05	
Mod[2]	1.0000000003414	
Mod[3]	1.00000054152602	
Arg[1]	180	
Arg[2]	0	
Arg[3]	180	

Figure 18: The **Numeric** window at the second PD bifurcation. The bifurcation parameter value is  $\beta = 0.5417461...$ 



Figure 19: The cycle branch in system (3) rooted at the Hopf point. Two critical cycles undergoing the period-doubling bifurcations are labeled by PD.

承 Plot2D - beta,Period 📃 🗖								- 🗆 🗵					
File	Edit	Vie	w	Insert	Tools	Desktop	Window	Help	MatCont				ъ
1	6		4	R	۹, ۱	् 🖑 (	🖵 🕲	<i>s</i> • •	3 1			]	
		40 r											
		35											
		30											
		25											
	p	20											
	erio	20											
	۵.												
		15 -					<hr/>						
		10											
		5											
		0											_
		0.5	1	0.512	0.514	4 0.516	0.518	0.52 beta	0.522	0.524	0.526	0.528	0.53

Figure 20: The cycle period near the homoclinic bifurcation.

indicating that in both cases the normal form coefficients are negative, so that stable double-period cycles are involved.

You get a cycle manifold shown in Figure 19. The period of the cycle rapidly increases when  $\beta$  approaches  $\beta_{\text{hom}} = 0.515489...$  To see this, open a **Plot2D** window (see Figure 20) with the axes beta and Period and the plotting region

Abscissa:	0.51	0.53
Ordinate:	0.0	35.0

and apply MatCont|Redraw Curve.

Actually, the limit cycle approaches a homoclinic orbit to the second equilibrium (x, y, z) = (1, 0, 0) of (3), which is a global bifurcation<sup>1</sup>. Below  $\beta_{\text{hom}}$  no cycle exists. Near the homoclinic bifurcation, the computation of the cycle and its multipliers becomes inaccurate. The loss of accuracy can be seen in the **Numeric** window, where no multiplier close to 1 is present at the last computed point.

#### 3.4 Continuation of the double cycle from the PD-point

Using **Select**|**Initial point**, take the first PD: **Period Doubling** point in the computed above curve as initial.

Adjust the **Plot3D** window by setting the visibility limits for **beta** as follows:

#### Abscissa: 0.5 0.63

<sup>1</sup>At  $\beta = \beta_{\text{hom}}$ , this equilibrium is a saddle-focus with the saddle quantity  $\sigma < 0$ . Thus, according to Shilnikov's Theorem, from this homoclinic orbit only one limit cycle bifurcates - the one we computed.



Figure 21: The branch of stable doubled cycles connects two PD points.

In the **Starter** window, set the number of mesh points **ntst** to 80, increase the **amplitude** to 0.005, and check only **Branch** Point of Cycles (BPC) in the Monitor Singularities section.

In the **Continuer** window, increase MaxTestIters to 30, and make sure that MaxStepsize remains equal to 0.7.

Click **Compute**|**Forward** and continue the doubled cycle bifurcating from the first PD-point at  $\beta = \beta_{PD,1}$ . This cycle remains stable until at (approximately)  $\beta = \beta_{PD,2}$  a branching point cycle (BPC) is detected. This is not surprising, since the PD-bifurcation for the original limit cycles corresponds to a branching point for the doubled cycles. Stop computations at BPC, clear **Plot3D** window and make **MatCont**|**Redraw Curve** to get Figure 21.

Exit MatCont.

### 4 Additional Problems

A. Study numerically limit cycles in the system

$$\begin{cases} \dot{x} &= \mu x - y - xz, \\ \dot{y} &= x + \mu y, \\ \dot{z} &= -z + y^2 + x^2 z, \end{cases}$$

that is another model of a feedback control system.

B. Consider the following *predator-prey* model

$$\begin{cases} \dot{x} = x - \frac{xy}{1 + \alpha x}, \\ \dot{y} = -y + \frac{xy}{1 + \alpha x} - \delta y^2. \end{cases}$$

1. Prove that the following polynomial system

$$\begin{cases} \dot{x} = x(1+\alpha x) - xy, \\ \dot{y} = -(y+\delta y^2)(1+\alpha x) + xy, \end{cases}$$
(4)

has the same orbits in the positive quadrant as the original model. Derive an explicit condition on  $(\alpha, \delta)$  for system (4) to have a positive equilibrium with one zero eigenvalue. Derive a similar condition for (4) to have a positive equilibrium with a pair of purely imaginary eigenvalues.

2. Introduce new variables

$$\begin{cases} \xi = \ln x, \\ \eta = \ln y, \end{cases}$$

in which the original system becomes:

$$\begin{cases} \dot{\xi} = 1 - \frac{\exp(\eta)}{1 + \alpha \exp(\xi)}, \\ \dot{\eta} = -1 + \frac{\exp(\xi)}{1 + \alpha \exp(\xi)} - \delta \exp(\eta). \end{cases}$$
(5)

Fix  $\alpha = 0.3$  and study numerically limit cycles of (5), when the parameter  $\delta$  varies. *Hint*: Begin with finding an equilibrium at  $\delta = 0.35$  by integration.

- 3. Relate your analytical and numerical results.
- C. Consider the following *predator-double prey* system:

$$\begin{cases} \dot{x} &= x(2.4 - x - 6y - 4z), \\ \dot{y} &= y(\beta - x - y - 10z), \\ \dot{z} &= -z(1 - 0.25x - 4y + z), \end{cases}$$

modelling dynamics of two prey populations affected by a predator.

- 1. Starting from  $\beta = 1.77$ , find its *positive* equilibrium by orbit integration.
- 2. Continue the equilibrium with respect to  $\beta$  until it exhibits a Hopf bifurcation.
- 3. Continue a limit cycle from the Hopf point and monitor the dependence of its period upon  $\beta$ . *Hint*: Set ntst to a high value.
- 4. Plot the cycle at different period values and try to understand its asymptotic shape. *Hint*: Compute and analyze the equilibria located on the coordinate planes.
- D. Consider the famous Lorenz system

$$\begin{cases} \dot{x} = \sigma(-x+y), \\ \dot{y} = rx - y - xz, \\ \dot{z} = -bz + xy, \end{cases}$$

with the standard parameter values  $\sigma = 10, b = \frac{8}{3}$  and r > 0. Use MATCONT to analyse its simplest limit cycles numerically.

- 1. Compute a critical parameter value  $r_{BP}$ , at which the trivial equilibrium (0, 0, 0) undergoes a *symmetric* pitchfork bifurcation.
- 2. Compute a critical parameter value  $r_{\rm H}$ , corresponding to a Hopf bifurcation of *nontrivial* equilibria.
- 3. Continue the limit cycle born at the Hopf bifurcation with respect to r and find out what happens to it. Plot the cycle period as function of r, and monitor stability.
- 4. Demonstrate by numerical integration that for r = 400 the system has a stable symmetric limit cycle and determine its period approximately. Continue this cycle with respect to r and find the critical parameter value  $r_{\text{BPC}}$  corresponding to a *branch point* of cycles (symmetry breaking). Hint: Use the procedure to start LC continuation from a simulation as done in Section 1.

Derive explicit formulas for  $r_{\rm BP}$  and  $r_{\rm H}$  as functions of  $(\sigma, b)$  and verify the numerical values obtained with MATCONT.