

# Lecture 2

## Equilibrium bifurcations of ODEs and their numerical analysis

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# 1. Equilibria of ODEs and their simplest (codim 1) bifurcations

- Consider a smooth ODE system

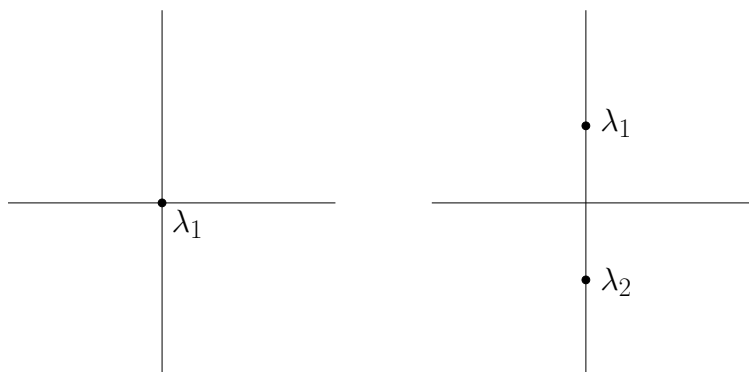
$$\dot{u} = f(u, \alpha), \quad u \in \mathbb{R}^n, \alpha \in \mathbb{R}^m.$$

- An equilibrium  $u_0$  satisfies

$$f(u_0, \alpha_0) = 0$$

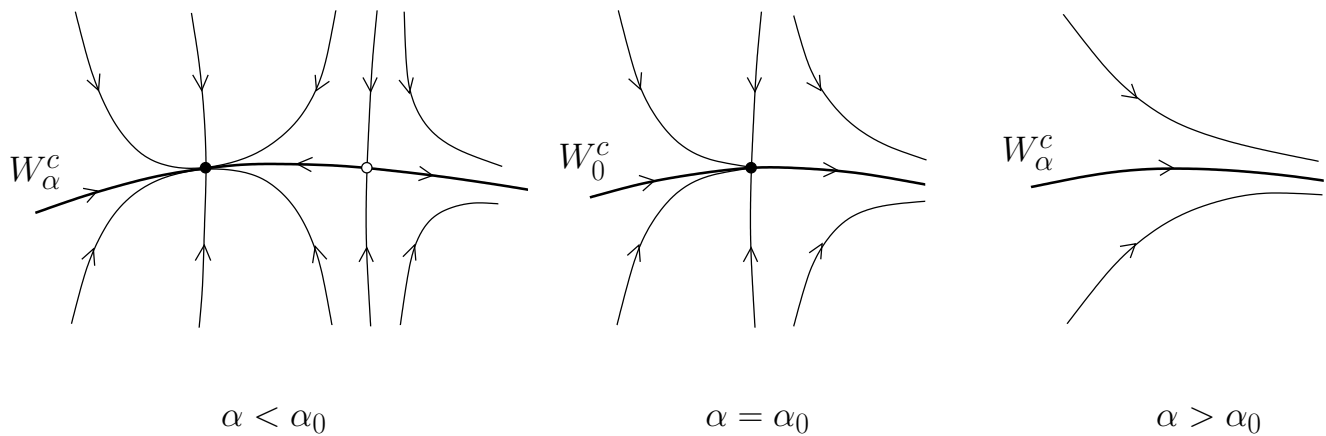
and its Jacobian matrix  $A = f_u(u_0, \alpha_0)$  has eigenvalues  $\{\lambda_1, \lambda_2, \dots, \lambda_n\}$ .

- Critical cases:



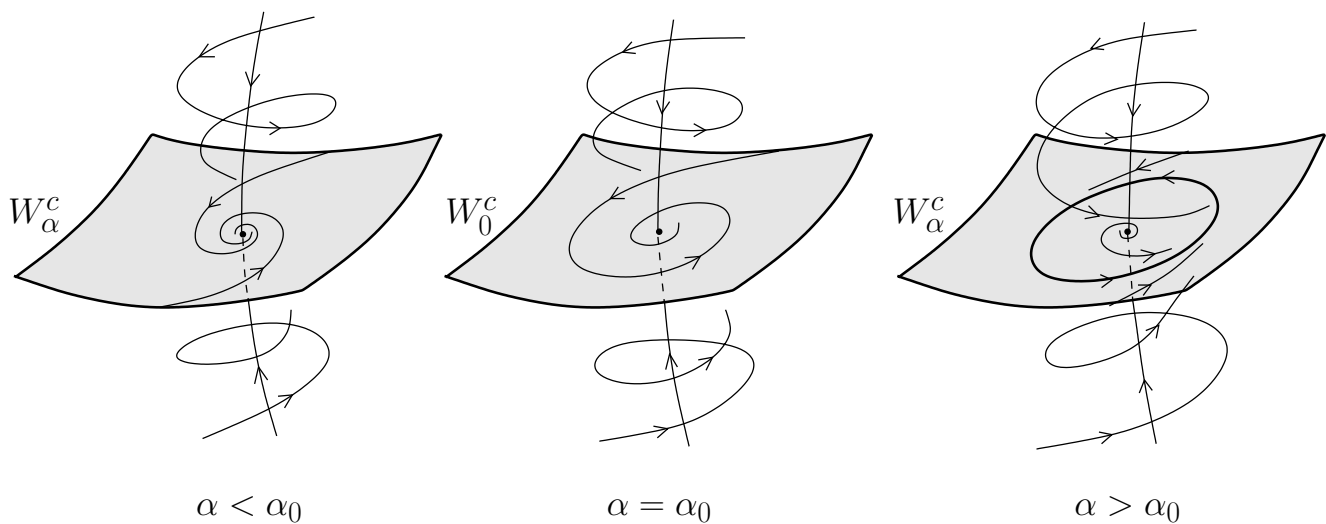
- **Fold (LP):**  $\lambda_1 = 0$ ;
- **Andronov-Hopf (H):**  $\lambda_{1,2} = \pm i\omega_0$ ,  
 $\omega_0 > 0$ .

- **Generic LP bifurcation:**  $\lambda_1 = 0$



Collision of two equilibria.

- **Generic H bifurcation:**  $\lambda_{1,2} = \pm i\omega_0$



Birth of a limit cycle.

## 2. Detection of LP and H bifurcations

- Monitor eigenvalues of  $A(u, \alpha) = f_u(u, \alpha)$  along the **equilibrium curve**

$$f(u, \alpha) = 0, \quad u \in \mathbb{R}^n, \quad \alpha \in \mathbb{R}.$$

- Test function for LP:  $\psi_{LP} = V_{n+1}$ , the  $\alpha$ -component of the normalized tangent vector to the equilibrium curve in the  $(u, \alpha)$ -space.
- Test function for H:

$$\psi_H = \det(2A(u, \alpha) \odot I_n),$$

where  $\odot$  denotes the **bialternate matrix product** with elements

$$(A \odot B)_{(i,j),(k,l)} = \frac{1}{2} \left\{ \begin{vmatrix} a_{ik} & a_{il} \\ b_{jk} & b_{jl} \end{vmatrix} + \begin{vmatrix} b_{ik} & b_{il} \\ a_{jk} & a_{jl} \end{vmatrix} \right\},$$

where  $i > j, k > l$ .

## Wedge product of vectors

- Two index pairs  $(i, j), (k, l)$  are listed in the **lexicographic order** if either  $i < k$  or ( $i = k$  and  $j < l$ ).
- The **wedge product** of two vectors  $v, w \in \mathbb{C}^n$  is a vector  $v \wedge w \in \mathbb{C}^m$ ,  $m = \frac{n(n-1)}{2}$ , with the components:

$$(v \wedge w)_{(i,j)} = v_i w_j - v_j w_i, \quad n \geq i > j \geq 1,$$

listed in the lexicographic order of their index pairs.

- For any  $v, w, w^{1,2} \in \mathbb{C}^n$ ,  $\lambda \in \mathbb{C}$ :  $v \wedge w = -w \wedge v$  and

$$v \wedge (\lambda w) = \lambda(v \wedge w), \quad v \wedge (w^1 + w^2) = v \wedge w^1 + v \wedge w^2.$$

- If  $e^i \in \mathbb{C}^n$ ,  $n \geq i \geq 1$ , form a basis in  $\mathbb{C}^n$ , then  $e^i \wedge e^j \in \mathbb{C}^m$ ,  $n \geq i > j \geq 1$ , form a basis in  $\mathbb{C}^m$ .

## Bialternate matrix product

- The matrix of the linear transformation of  $\mathbb{C}^m$  defined by

$$(v \wedge w) \mapsto (A \odot B)(v \wedge w) = \frac{1}{2}(Av \wedge Bw - Aw \wedge Bv)$$

in the standard basis  $\{e^i \wedge e^j\}$  is called the **bialternate product** of two matrices  $A, B \in \mathbb{C}^{n \times n}$ .

- **Stéphanos Theorem** *If  $A \in \mathbb{C}^{n \times n}$  has eigenvalues  $\lambda_1, \lambda_2, \dots, \lambda_n$ , then*

- (i)  $A \odot A$  has eigenvalues  $\lambda_i \lambda_j$ ,
- (ii)  $2A \odot I_n$  has eigenvalues  $\lambda_i + \lambda_j$ ,

where  $n \geq i > j \geq 1$ .

Indeed, if  $\{v^i\}$  are linearly-independent eigenvectors of  $A$ , then  $v^i \wedge v^j$  is an eigenvector of both  $A \odot A$  and  $2A \odot I_n$ .

- For two nonsingular matrices  $A$  and  $B$ :

$$\begin{aligned}(AB) \odot (AB) &= (A \odot A)(B \odot B), \\ (A \odot A)^{-1} &= A^{-1} \odot A^{-1}.\end{aligned}$$

### **3. Continuation of LP and Hopf bifurcations**

3.1. Bordering technique

3.2. Continuation of LP bifurcation

3.3. Continuation of Hopf bifurcation



### 3.1. Bordering technique

Let  $M \in \mathbb{R}^{n \times n}$ ,  $v_j, b_j, c_j \in \mathbb{R}^n$ ,  $g_{ij}, d_{ij} \in \mathbb{R}$

- Suppose the following system has invertible matrix:

$$\begin{pmatrix} M & b_1 \\ c_1^T & d_{11} \end{pmatrix} \begin{pmatrix} v_1 \\ g_{11} \end{pmatrix} = \begin{pmatrix} 0 \\ 1 \end{pmatrix}.$$

Then  $M$  has rank defect 1 if and only if  $g_{11} = 0$ . Indeed, by Cramer's rule

$$g_{11} = \frac{\det M}{\det \begin{pmatrix} M & b_1 \\ c_1^T & d_{11} \end{pmatrix}}.$$

- Suppose the following system has invertible matrix:

$$\begin{pmatrix} M & b_1 & b_2 \\ c_1^T & d_{11} & d_{12} \\ c_2^T & d_{21} & d_{22} \end{pmatrix} \begin{pmatrix} v_1 & v_2 \\ g_{11} & g_{12} \\ g_{21} & g_{22} \end{pmatrix} = \begin{pmatrix} 0 & 0 \\ 1 & 0 \\ 0 & 1 \end{pmatrix}.$$

Then  $M$  has rank defect 2 if and only if

$$g_{11} = g_{12} = g_{21} = g_{22} = 0.$$

## 3.2. Continuation of LP bifurcation

- At a generic LP bifurcation  $A(u, \alpha) = f_u(u, \alpha)$  has rank defect 1.
- Defining system:  $x = (u, \alpha) \in \mathbb{R}^{n+2}$

$$\begin{cases} f(u, \alpha) = 0, \\ G(u, \alpha) = 0, \end{cases}$$

where  $G$  is computed by solving the *bordered system*

$$\begin{pmatrix} A(u, \alpha) & p_1 \\ q_1^\top & 0 \end{pmatrix} \begin{pmatrix} q \\ G \end{pmatrix} = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

- Vectors  $q_1, p_1 \in \mathbb{R}^n$  are adapted along the LP-curve to make the matrix of the linear system nonsingular.
- $(G_u, G_\alpha)$  can be computed efficiently using the adjoint linear system.

## Derivatives of $G$

The  $\alpha$ -derivative of the bordered system

$$\begin{pmatrix} A(u, \alpha) & p_1 \\ q_1^\top & 0 \end{pmatrix} \begin{pmatrix} q_\alpha \\ G_\alpha \end{pmatrix} + \begin{pmatrix} A_\alpha(u, \alpha) & 0 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} q \\ G \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

implies

$$\begin{pmatrix} A(u, \alpha) & w_1 \\ q_1^\top & 0 \end{pmatrix} \begin{pmatrix} q_\alpha \\ G_\alpha \end{pmatrix} = - \begin{pmatrix} A_\alpha(u, \alpha) & 0 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} q \\ G \end{pmatrix}$$

Multiplication from the left by  $(p^\top \ h)$  satisfying

$$\begin{pmatrix} A^\top(u, \alpha) & q_1 \\ p_1^\top & 0 \end{pmatrix} \begin{pmatrix} p \\ h \end{pmatrix} = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

gives

$$G_\alpha = -p^\top A_\alpha(u, \alpha)q = -\langle p, A_\alpha(u, \alpha)q \rangle.$$

### 3.3. Continuation of Hopf bifurcation

- At a generic Hopf bifurcation  $A^2(u, \alpha) + \omega_0^2 I_n$  has rank defect 2.

- Defining system:  $x = (u, \alpha, \kappa) \in \mathbb{R}^{n+3}$

$$\begin{cases} f(u, \alpha) = 0, \\ G_{11}(u, \alpha, \kappa) = 0, \\ G_{22}(u, \alpha, \kappa) = 0, \end{cases}$$

where  $\kappa = \omega_0^2$  and  $G_{ij}$  are computed by solving

$$\begin{pmatrix} A^2(u, \alpha) + \kappa I_n & p_1 & p_2 \\ q_1^\top & 0 & 0 \\ q_2^\top & 0 & 0 \end{pmatrix} \begin{pmatrix} r & s \\ G_{11} & G_{12} \\ G_{21} & G_{22} \end{pmatrix} = \begin{pmatrix} 0 & 0 \\ 1 & 0 \\ 0 & 1 \end{pmatrix}$$

- Vectors  $q_{1,2}, p_{1,2} \in \mathbb{R}^n$  are adapted to ensure unique solvability.
- Efficient computation of derivatives of  $G_{ij}$  is possible.

## Remarks on continuation of bifurcations

- For each defining system holds: *Simplicity of the bifurcation* + *Transversality*  $\Rightarrow$  *Regularity of the defining system*.
- Border adaptation using solutions of the adjoint linear system.

- Alternatives to bordering for LP:

$$\left\{ \begin{array}{l} f(u, \alpha) = 0, \\ f_u(u, \alpha)q = 0, \\ \langle q, q_0 \rangle - 1 = 0 \end{array} \right. \quad \text{or} \quad \left\{ \begin{array}{l} f(u, \alpha) = 0, \\ \det(f_u(u, \alpha)) = 0. \end{array} \right.$$

- Alternatives to bordering for H:

$$\left\{ \begin{array}{l} f(u, \alpha) = 0, \\ f_u(u, \alpha)q + \omega p = 0, \\ f_u(u, \alpha)p - \omega q = 0, \\ \langle q, q_0 \rangle + \langle p, p_0 \rangle - 1 = 0, \\ \langle q, p_0 \rangle - \langle q_0, p \rangle = 0 \end{array} \right.$$

or

$$\left\{ \begin{array}{l} f(u, \alpha) = 0, \\ \det(2f_u(u, \alpha) \odot I_n) = 0. \end{array} \right.$$

## **4. Computation of normal forms for LP and Hopf bifurcations**

4.1. Normal forms on center manifolds

4.2. Fredholm's Alternative

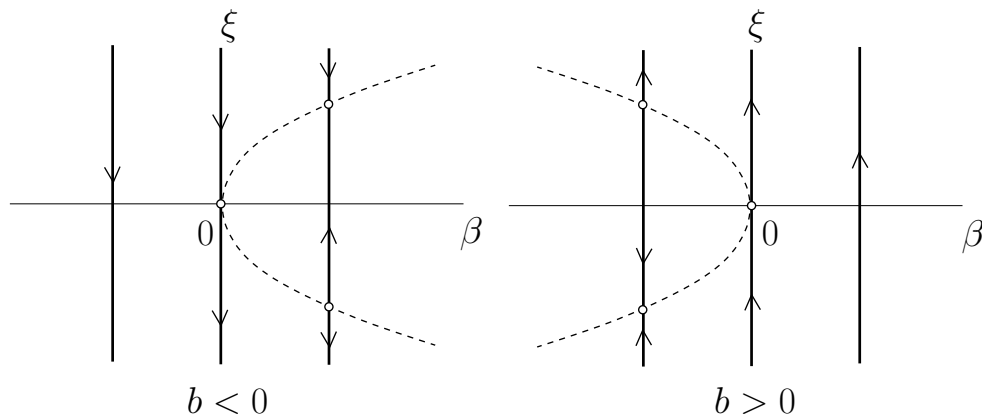
4.3. Critical LP-coefficient

4.4. Critical H-coefficient

4.5. Approximation of multilinear forms by finite differences

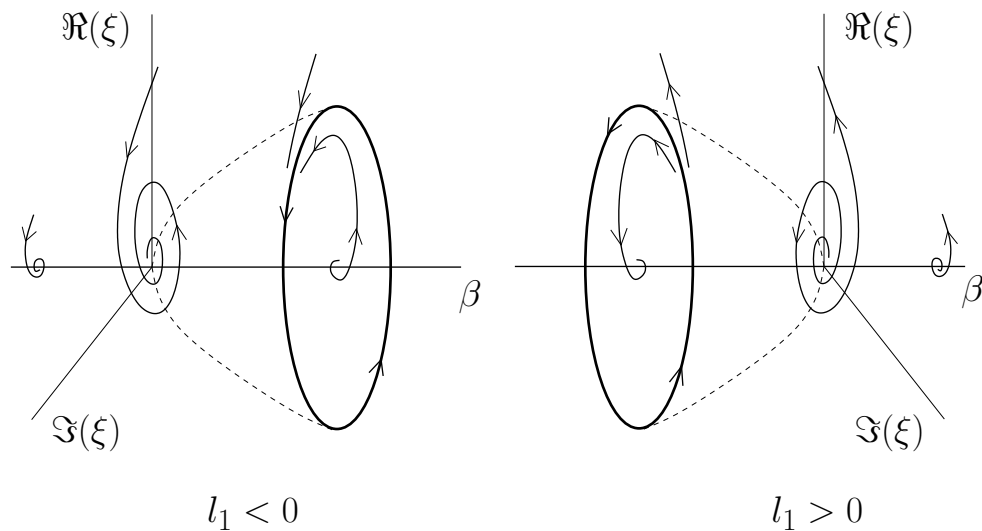
## 4.1. Normal forms on center manifolds

- LP:  $\dot{\xi} = \beta + b\xi^2$ ,  $b \neq 0$



Equilibria:  $\beta + b\xi^2 = 0 \Rightarrow \xi_{1,2} = \pm\sqrt{-\frac{\beta}{b}}$

- H:  $\dot{\xi} = (\beta + i\omega)\xi + c\xi|\xi|^2$ ,  $l_1 = \frac{1}{\omega}\Re(c) \neq 0$



Limit cycle:

$$\begin{cases} \dot{\rho} = \rho(\beta + \Re(c)\rho^2), \\ \dot{\varphi} = \omega + \Im(c)\rho^2, \end{cases} \Rightarrow \rho_0 = \sqrt{-\frac{\beta}{\Re(c)}}$$

## 4.2. Fredholm's Alternative

- **Lemma 1** *The linear system  $Ax = b$  with  $b \in \mathbb{R}^n$  and a singular  $n \times n$  real matrix  $A$  is solvable if and only if  $\langle p, b \rangle = 0$  for all  $p$  satisfying  $A^T p = 0$ .*

Indeed,  $\mathbb{R}^n = L \oplus R$  with  $L \perp R$ , where

$$L = \mathcal{N}(A^T) = \{p \in \mathbb{R}^n : A^T p = 0\}$$

and

$$R = \{x \in \mathbb{R}^n : x = Ay \text{ for some } y \in \mathbb{R}^n\}.$$

The proof is completed by showing that the orthogonal complement  $L^\perp$  to  $L$  coincides with  $R$ .

- In the complex case:

$$\begin{aligned}\mathbb{R}^n &\Rightarrow \mathbb{C}^n \\ \langle p, b \rangle &= \bar{p}^T b \\ A^T &\Rightarrow A^* = \bar{A}^T\end{aligned}$$



### 4.3. Critical LP-coefficient $b$

- Let  $Aq = A^T p = 0$  with  $\langle q, q \rangle = \langle p, q \rangle = 1$ .
- Write the RHS at the bifurcation as

$$F(u) = Au + \frac{1}{2}B(u, u) + O(\|u\|^3),$$

and locally represent the center manifold  $W_0^c$  as the graph of a function  $H : \mathbb{R} \rightarrow \mathbb{R}^n$ ,

$$u = H(\xi) = \xi q + \frac{1}{2}h_2 \xi^2 + O(\xi^3), \quad \xi \in \mathbb{R}, \quad h_2 \in \mathbb{R}^n.$$

The restriction of  $\dot{u} = F(u)$  to  $W_0^c$  is

$$\dot{\xi} = G(\xi) = b\xi^2 + O(\xi^3).$$

- The invariance of the center manifold  $H_\xi(\xi)\dot{\xi} = F(H(\xi))$  implies

$$H_\xi(\xi)G(\xi) = F(H(\xi))$$

Substitute all expansions into this **homological equation** and collect the coefficients of the  $\xi^j$ -terms.

We have

$$\begin{aligned} A(\xi q + \frac{1}{2}h_2\xi^2) + \frac{1}{2}B(\xi q, \xi q) + O(|\xi|^3) \\ = b\xi^2q + b\xi^3h_2 + O(|\xi|^4) \end{aligned}$$

- The  $\xi$ -terms give the identity:  $Aq = 0$ .
- The  $\xi^2$ -terms give the equation for  $h_2$ :

$$Ah_2 = -B(q, q) + 2bq.$$

It is singular and its **Fredholm solvability**

$$\langle p, -B(q, q) + 2bq \rangle = 0$$

implies

$$b = \frac{1}{2}\langle p, B(q, q) \rangle$$

#### 4.4. Critical H-coefficient $c$

- $Aq = i\omega_0 q, A^\top p = -i\omega_0 p, \langle q, q \rangle = \langle p, p \rangle = 1.$

- Write

$$F(u) = Au + \frac{1}{2}B(u, u) + \frac{1}{3!}C(u, u, u) + O(\|u\|^4)$$

and locally represent the center manifold  $W_0^c$  as the graph of a function  $H : \mathbb{C} \rightarrow \mathbb{R}^n,$

$$u = H(\xi, \bar{\xi}) = \xi q + \bar{\xi} \bar{q} + \sum_{2 \leq j+k \leq 3} \frac{1}{j!k!} h_{jk} \xi^j \bar{\xi}^k + O(|\xi|^4).$$

The restriction of  $\dot{u} = F(u)$  to  $W_0^c$  is

$$\dot{\xi} = G(\xi, \bar{\xi}) = i\omega_0 \xi + c\xi|\xi|^2 + O(|\xi|^4).$$

- The invariance of  $W_0^c$

$$H_\xi(\xi, \bar{\xi})\dot{\xi} + H_{\bar{\xi}}(\xi, \bar{\xi})\dot{\bar{\xi}} = F(H(\xi, \bar{\xi}))$$

implies

$$H_\xi(\xi, \bar{\xi})G(\xi, \bar{\xi}) + H_{\bar{\xi}}(\xi, \bar{\xi})\bar{G}(\xi, \bar{\xi}) = F(H(\xi, \bar{\xi})).$$

- Quadratic  $\xi^2$ - and  $|\xi|^2$ -terms give

$$\begin{aligned} h_{20} &= (2i\omega_0 I_n - A)^{-1} B(q, q), \\ h_{11} &= -A^{-1} B(q, \bar{q}). \end{aligned}$$

- Cubic  $w^2 \bar{w}$ -terms give the singular system

$$\begin{aligned} (i\omega_0 I_n - A)h_{21} &= C(q, q, \bar{q}) \\ &\quad + B(\bar{q}, h_{20}) + 2B(q, h_{11}) \\ &\quad - 2cq. \end{aligned}$$

The solvability of this system implies

$$\begin{aligned} c &= \frac{1}{2} \langle p, C(q, q, \bar{q}) \\ &\quad + B(\bar{q}, (2i\omega_0 I_n - A)^{-1} B(q, q)) \\ &\quad - 2B(q, A^{-1} B(q, \bar{q})) \rangle \end{aligned}$$

- The **first Lyapunov coefficient**

$$l_1 = \frac{1}{\omega_0} \Re(c).$$

## 4.5. Approximation of multilinear forms by finite differences

- Finite-difference approximation of directional derivatives:

$$B(q, q) = \frac{1}{h^2} [f(u_0 + hq, \alpha_0) + f(u_0 - hq, \alpha_0)] + O(h^2)$$
$$C(r, r, r) = \frac{1}{8h^3} [f(u_0 + 3hr, \alpha_0) - 3f(u_0 + hr, \alpha_0) + 3f(u_0 - hr, \alpha_0) - f(u_0 - 3hr, \alpha_0)] + O(h^2).$$

- Polarization identities:

$$B(q, r) = \frac{1}{4} [B(q + r, q + r) - B(q - r, q - r)],$$

$$C(q, q, r) = \frac{1}{6} [C(q + r, q + r, q + r) - C(q - r, q - r, q - r)] - \frac{1}{3} C(r, r, r).$$

## 5. Detection of codim 2 bifurcations

- codim 2 cases along the LP-curve:
  - **Bogdanov-Takens (BT)**:  $\lambda_{1,2} = 0$   
( $\psi_{BT} = \langle p, q \rangle$  with  $\langle q, q \rangle = \langle p, p \rangle = 1$ )
  - **fold-Hopf (ZH)**:  $\lambda_1 = 0, \lambda_{2,3} = \pm i\omega_0$   
( $\psi_{ZH} = \det(2A \odot I_n)$ )
  - **cusp (CP)**:  $\lambda_1 = 0, b = 0$  ( $\psi_{CP} = b$ )
- Critical cases along the H-curve:
  - **Bogdanov-Takens (BT)**:  $\lambda_{1,2} = 0$   
( $\psi_{BT} = \kappa$ )
  - **fold-Hopf (ZH)**:  $\lambda_{1,2} = \pm i\omega_0, \lambda_3 = 0$   
( $\psi_{ZH} = \det A$ )
  - **double Hopf (HH)**:  $\lambda_{1,2} = \pm i\omega_0, \lambda_{3,4} = \pm i\omega_1$   
( $\psi_{HH} = \det(2A^\perp \odot I_{n-2})$ )
  - **Bautin (GH)**:  $\lambda_{1,2} = \pm i\omega_0, l_1 = 0$   
( $\psi_{GH} = l_1$ )