

REMINDER:  $E \rightarrow M$  v.b

• connection  $\nabla$  on  $E$ :  $\mathfrak{X}(M) \times \Gamma(E) \rightarrow \Gamma(E), (X, s) \mapsto \nabla_X(s)$  [-1-]

which is bilinear and:  $\nabla_{fX}(s) = f \nabla_X(s), \nabla_X(fs) = f \nabla_X(s) + L_X(f)s$

• dual picture:

$$d_\nabla: \Gamma(E) \rightarrow \Omega^1(M; E)$$

which is linear and Leibniz:

$$d_\nabla(fs) = f d_\nabla(s) + df \cdot s$$

Relation:

$$E = M \times \mathbb{R}$$

$$d_\nabla(s)(X) = \nabla_X(s)$$

$$\nabla_X(f) = L_X(f) + f \cdot \omega(X)$$

$$\frac{Dv}{dt} = 0 \text{ above } \mathcal{F}$$

• locally, w.r.t. frame  $e = \{e_1, \dots, e_r\}$  of  $E$  over  $U$ . [-2-]

$$\nabla_X(e_i) = \sum_j \omega_j^i(X) e_j \text{ for some } \omega_j^i \in \Omega^1(U)$$



$$\nabla_X(f) = L_X(f) + f \cdot \omega(X)$$

$$\frac{\nabla u}{dt} = 0 \text{ above } \gamma$$

• locally, w.r.t. frame  $e = \{e_1, \dots, e_r\}$  of  $E$  over  $U$ . [2-]

$$\nabla_X(e_i) = \sum_j \omega_j^i(X) e_j \quad \text{for some } \omega = (\omega_{i,j}^k) \in M_r(\mathbb{R}^1(U))$$

$\omega \text{ w.r.t. } (e)$

Then, for arbitrary  $s$ , writing  $s|_U = \sum f^i e_i$  ( $f^i \in C^\infty(U)$ )

$$\Rightarrow \nabla_X(s) = \sum_i \left( L_X(f^i) + \sum_j f^j \omega_j^i(X) \right) e_i \quad \text{over } U$$

• for  $u: I \xrightarrow{\pi} E$  with base path  $\gamma = \pi \circ u$  ( $i.e. u(t) \in E_{\gamma(t)}$ )  
 $u = \text{"path above } \gamma\text{"}$

$\Rightarrow$  can talk about  $\frac{\nabla u}{dt}: I \rightarrow E$ , a path above the same  $\gamma$

Locally: writing  $u(t) = \sum u^i(t) e_i(\gamma(t))$  ( $u^i: I \rightarrow \mathbb{R}$ )  $\Rightarrow$

$$\Rightarrow \frac{\nabla u}{dt}(t) = \sum_i \left( \frac{du^i}{dt}(t) + \sum_j u^j(t) \omega_j^i(\dot{\gamma}(t)) \right) e_i(\gamma(t))$$

Def  
(or  
Rk:

If we  
 $\frac{dU}{dt} = A(t)$

Prop  
 $\Rightarrow (A$



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 • connection  $\nabla$  on  $E$ :  
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$$\Gamma(M) \times \Gamma(E) \rightarrow \Gamma(E), (X, s) \mapsto \nabla_X(s)$$

$$\nabla_{fX}(s) = f \nabla_X(s), \quad \nabla_X(fs) = f \nabla_X(s) + L_X(f)s$$

• dual picture:

$$d\nabla: \Gamma(E) \rightarrow \Omega^1(M; E)$$

which is linear and

Leibniz:

$$d\nabla(fs) = f d\nabla(s) + df \cdot s$$

Relation:

$$d\nabla(s)(X) = \nabla_X(s)$$

$$E = M \times \mathbb{R}$$

$$\nabla_X(f) = \nabla_X(f) + f \cdot \omega(X)$$

$$\frac{d\nabla}{dt} = 0 \text{ above } \gamma$$

• locally, w.r.t. frame  $e = \{e_1, \dots, e_r\}$  of  $E$  over  $U$ .

$$\nabla_X(e_i) = \sum_j \omega_j^i(X) e_j \quad \text{for some } \omega = (\omega_{ij}) \in \mathcal{M}_r(\mathbb{R}^2)$$

Then, for arbitrary  $s$ , writing  $s|_U = \sum f^i e_i$  ( $f^i \in C^\infty(U)$ )  
 $\Rightarrow \nabla_X(s) = \sum_i \left( L_X(f^i) + \sum_j f^j \omega_j^i(X) \right) e_i$  over  $U$

• for  $u: I \rightarrow E$  with base path  $\gamma = \pi \circ u$  ( $i \in u(t) \in E_{\gamma(t)}$ )  
 $\Rightarrow$  can talk about  $\frac{du}{dt}: I \rightarrow E$ , a path above the same  $\gamma$   
 Locally: writing  $u(t) = \sum u^i(t) e_i(\gamma(t))$  ( $u^i: I \rightarrow \mathbb{R}$ )

$$\Rightarrow \frac{du}{dt}(t) = \sum_i \left( \frac{du^i}{dt}(t) + \sum_j u^j(t) \omega_j^i(\gamma(t)) \right) e_i(\gamma(t))$$

Def:  $\nabla$   
 (or  $\nabla$ -)

Rk: Local

If we fix

$$\frac{du}{dt} = A(t)u(t)$$

Prop:  $G$

$$\Rightarrow (\forall) u_0 \in$$



$$p(u) = \sum_i \frac{\langle u, e_i \rangle}{\|e_i\|^2} e_i$$

$$u - p(u) \perp V$$

$$\langle u - p(u), e_i \rangle = 0 \quad (i=1, \dots, r)$$

$$\langle u, e_i \rangle = \langle p(u), e_i \rangle = \lambda^i \|e_i\|^2$$

$$p: \mathbb{R}^n \rightarrow V$$

$$p(u) = \sum_{i=1}^r \lambda^i e_i + \sum_{i=r+1}^n \lambda^i e_i$$

$Rk \parallel$  is a "V"

(2)

Def: Given  $\nabla$ , a path  $u: I \rightarrow E$  is called  $\nabla$ -parallel (or  $\nabla$ -horizontal, or  $\nabla$ -constant) if  $\frac{\nabla u}{dt} = 0$ .

Rk: Locally:  $u = \sum (u^i(t) e_i(t))$ , the condition on the  $u^i$ 's reads

$$\frac{du^i}{dt}(t) = - \sum_j u^j(t) \omega_j^i(\dot{\gamma}(t)) \quad 1 \leq i \leq r$$

If we fix  $\gamma \Rightarrow$  an equation of type

$$\frac{dU}{dt} = A(t)U(t) \quad \frac{d}{dt} \underbrace{(u^1, \dots, u^r)}_{U(t)} = A(t) \underbrace{(u^1, \dots, u^r)}_{U(t)}$$

always has <sup>many</sup> solution over the entire  $I$  on which  $\gamma$  is defined with sol

$$u(t) = \exp\left(\int_{t_0}^t A\right) \cdot u_0$$

for any  $t_0, u_0$ .  
 $u(t_0) = u_0$ .

Prop: Given  $\nabla$  and  $\gamma: I \rightarrow E, t_0 \in I \Rightarrow$

$$\Rightarrow (\forall) u_0 \in E_{\gamma(t_0)} \quad \exists! u: I \rightarrow E \text{ st } \begin{cases} u = \nabla\text{-parallel} \\ u(t_0) = u_0 \end{cases}$$

(\*)

Def The to to to

Proposition

(linear) is

rel:  $\nabla$  linear

with  $\frac{\nabla u}{dt} =$



" $\nabla$  being compatible with a geom-structro"

d  $\nabla$ -parallel

$u$ 's reads  
 $1 \leq i \leq r$

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$$u(t) = \exp\left(\int_{t_0}^t A\right) \cdot u_0$$

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Def: The  $\parallel$ -transport of  $\nabla$  along  $\gamma$ , from  $t_0$  to  $t_1$  (where  $t_0, t_1 \in I$ ) is the map

$$T_{\gamma}^{t_0, t_1}: E_{\gamma(t_0)} \rightarrow E_{\gamma(t_1)}$$

$\downarrow \psi$                        $\downarrow \psi$   
 $v_0 \in M_0 \longmapsto u(t_1)$  where  $u$  is the sol. of (\*)

Proposition: Each such  $T_{\gamma}^{t_0, t_1}$  is a

linear isomorphism and

$$T_{\gamma}^{t, t} = Id_{E_{\gamma(t)}}$$

$$T_{\gamma}^{t_0, t_1} \circ T_{\gamma}^{t_1, t_0} = Id_{E_{\gamma(t_0)}}$$

$$T_{\gamma}^{t_1, t_2} \circ T_{\gamma}^{t_0, t_1} = T_{\gamma}^{t_0, t_2}$$

pf:  $\textcircled{1}$  Linear:  $T_{\gamma}^{t_0, t_1}(u_0) + T_{\gamma}^{t_0, t_1}(v_0) = T_{\gamma}^{t_0, t_1}(u_0 + v_0)$   
 $(u+v)(t_1) = u(t_1) + v(t_1)$

with  $u$   
 $\frac{\nabla u}{dt} = 0, u(t_0) = u_0$        $\frac{\nabla v}{dt} = 0, v(t_0) = v_0 \implies \frac{\nabla(u+v)}{dt} = 0, (u+v)(t_0) = u_0 + v_0$



$$\frac{v_M}{dt} = 0, \text{ alt } \frac{v_M}{dt} = 0, \text{ alt } \frac{v_M}{dt} = 0, \text{ alt } \frac{v_M}{dt} = 0, \text{ alt } \frac{v_M}{dt} = 0$$

-5-

Corollary: Any vector bundle over a contractible space  $M$  is trivializable.

$$H: M \times [0, 1] \rightarrow M \text{ smooth}$$

$$H_t = H(\cdot, t): M \rightarrow M \text{ s.t. } \begin{cases} H(x, 0) = x_0 \text{ for some } x_0 \in M \\ H(x, 1) = x \quad (\forall) x \in M \end{cases}$$

$H_0 \sim H_1$  Equivalently, the identity map is homotopic to the const  $x_0$

$$H_1 = H(\cdot, 1)$$

$$\gamma_x = H(x, \cdot): [0, 1] \rightarrow M$$

Do  $g$ -transport to compare  $E_x$  to  $E_{x_0}$ .  $0 \mapsto x_0$   
 $1 \mapsto x$

Rk:  $\parallel$  is also useful to make sense of  $\nabla$  being compatible with a geom. structure

$V \subseteq \mathbb{R}^k$   
 $\langle \cdot, \cdot \rangle$  con. on  $\mathbb{R}^k$   
 orthogonal basis  $e_1, \dots, e_r$  of  $V$   
 $\text{pr}: \mathbb{R}^k \rightarrow V$   
 $\text{pr}(u) = \sum_{i=1}^r \lambda_i e_i$



called  $\nabla$ -parallel

$\frac{d}{dt} = 0$   
 on the  $u$ 's reads  
 $1 \leq i \leq r$

always has <sup>many</sup> solution  
 over the entire  $I$   
 on which  $\gamma$  is defined  
 with sol

$$u(t) = \exp\left(\int_{t_0}^t A\right) \cdot u_0$$

for any  $t_0, u_0$   
 $u(t_0) = u_0$

Def The  $\parallel$ -transport of  $\nabla$  along  $\gamma$ , from  $t_0$  to  $t_1$  (where  $t_0, t_1 \in I$ ) is the map

$$T_{\gamma}^{t_0, t_1}: E_{\gamma(t_0)} \rightarrow E_{\gamma(t_1)}$$

$\Downarrow \quad \Downarrow$   
 $v_0 \quad u_0 \quad \longmapsto \quad u(t_1)$  where  $u$  is the sol. of  $(*)$

Proposition: Each such  $T_{\gamma}^{t_0, t_1}$  is a linear isomorphism and

$$T_{\gamma}^{t_0, t_1} \circ T_{\gamma}^{t_1, t_0} = Id_{E_{\gamma(t_0)}}$$

$$T_{\gamma}^{t_1, t_2} \circ T_{\gamma}^{t_0, t_1} = T_{\gamma}^{t_0, t_2}$$

pf:  $\text{Linear}$   $T_{\gamma}^{t_0, t_1}(u_0) + T_{\gamma}^{t_0, t_1}(v_0) = T_{\gamma}^{t_0, t_1}(u_0 + v_0)$   
 with  $u$   $u(t_1)$   $v$   $v(t_1)$   $(u+v)(t_1) = u(t_1) + v(t_1)$   
 $\frac{D}{dt} u = 0, u(t_0) = u_0$   $\frac{D}{dt} v = 0, v(t_0) = v_0 \Rightarrow \frac{D}{dt}(u+v) = 0, (u+v)(t_0) = u_0 + v_0$

Corollary: Any vector bundle over a contractible space  $M$  is trivializable.

$$H: M \times [0, 1] \rightarrow M \text{ smooth}$$

s.t.  $\begin{cases} H(x, 0) = x_0 \\ H(x, 1) = x \end{cases}$  for some  $x_0 \in M$  ( $\forall x \in M$ )  
 $H_t = H(\cdot, t): M \rightarrow M$   
 $H_0 \sim H_1$

Equivalently, the identity map is homotopic to the const  $x_0$

$$H_1 = H(\cdot, 1)$$

$$H_0 = H(\cdot, 0)$$

$\gamma_x = H(x, \cdot): [0, 1] \rightarrow M$   
 Do  $\parallel$ -transport to compare  $E_x$  to  $E_{x_0}$ .  $0 \mapsto x_0$ ,  $1 \mapsto x$

Rk:  $\parallel$  is also useful to make sense of " $\nabla$  being compatible with a geom. structure"

$V \subseteq \mathbb{R}^k$   
 $pr: \mathbb{R}^k \rightarrow V$   
 $pr(u) = \sum_{i=1}^r u_i e_i + \sum_{j=r+1}^k u_j e_j$   
 $\langle \cdot, \cdot \rangle$  on  $\mathbb{R}^k$   
 Orthogonal basis  $e_1, \dots, e_r$  of  $V$



REMINDER:  $E \rightarrow M$  v.b.  $\square$   
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 which is bilinear and  $\nabla_X(s) = f \nabla_X(s)$ ,  $\nabla_X(fs) = f \nabla_X(s) + (Xf)s$

Corollary: Any vector bundle over a contractible space is trivializable  $\square$

• locally, with frame  $e = \{e_1, \dots, e_r\}$  of  $E$  over  $U$ .  
 $\nabla_X(e_i) = \sum_j \omega_j^i(X) e_j$  for some  $\omega_j^i = (\omega_{ij}^k) \in M_r(\mathbb{R}^{2n})$   
 Then, for arbitrary  $s$ , writing  $s|_U = \sum f^i e_i$  ( $f^i \in C^\infty(U)$ )  
 $\Rightarrow \nabla_X(s) = \sum_i \left( X(f^i) + \sum_j f^j \omega_j^i(X) \right) e_i$  over  $U$   
 • for  $u: I \rightarrow E$  with base path  $\gamma = \pi \circ u$  ( $i.e. u(t) \in E_{\gamma(t)}$ )  
 $\Rightarrow$  can talk about  $\frac{\nabla u}{dt}: I \rightarrow E$ , a path above the same  $\gamma$   
 Locally, writing  $u = \sum u^i(t) e_i(\gamma(t))$  ( $u^i: I \rightarrow \mathbb{R}$ )  
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 Rk: Locally  $u = \sum u^i(t) e_i(\gamma(t))$ , the condition on the  $u^i$ 's reads  
 $\frac{du^i}{dt}(t) + \sum_j u^j(t) \omega_j^i(\dot{\gamma}(t)) = 0$   $1 \leq i \leq r$   
 If we fix  $\gamma \Rightarrow$  an equation of type  
 $\frac{du}{dt} = A(t)u$   $\frac{d}{dt} \begin{pmatrix} u^1 \\ \vdots \\ u^r \end{pmatrix} = A(t) \begin{pmatrix} u^1 \\ \vdots \\ u^r \end{pmatrix}$   
 always has many solutions over the entire  $I$  on which  $\gamma$  is defined with sol  $u(t) = \exp\left(\int_{t_0}^t A\right) \cdot u_0$   
 Prop: Given  $\nabla$  and  $\gamma: I \rightarrow E$ ,  $t_0 \in I$   
 $\Rightarrow \exists! u \in E_{\gamma(t_0)}$   $\exists! M: I \rightarrow E$  s.t.  $\int u = \nabla$ -parallel above  $\gamma$   $u(t_0) = u_0$ .  
 $M(t_0) = M_0$

Def: The  $\parallel$ -transport of  $\nabla$  along  $\gamma$ , from  $t_0$  to  $t_1$  (where  $t_0, t_1 \in I$ ) is the map  
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 Proposition: Each such  $T_{\gamma}^{t_0, t_1}$  is a linear isomorphism and  $T_{\gamma}^{t_0, t_1} \circ T_{\gamma}^{t_1, t_2} = T_{\gamma}^{t_0, t_2}$   
 $T_{\gamma}^{t_0, t_1} = \text{Id}_{E_{\gamma(t_0)}}$   
 $T_{\gamma}^{t_0, t_1} \circ T_{\gamma}^{t_1, t_0} = \text{Id}_{E_{\gamma(t_1)}}$   
 $T_{\gamma}^{t_0, t_1}(u_0) + T_{\gamma}^{t_0, t_1}(v_0) = T_{\gamma}^{t_0, t_1}(u_0 + v_0)$   
 with  $u = u(t)$   $v = v(t)$   $(u+v)(t) = u(t) + v(t)$   
 $\frac{\nabla u}{dt} = 0, u(t_0) = u_0$   $\frac{\nabla v}{dt} = 0, v(t_0) = v_0 \Rightarrow \frac{\nabla(u+v)}{dt} = 0, (u+v)(t_0) = u_0 + v_0$



The space of  $k$ -forms <sup>(G-)</sup> on  $M$  with coefficients in  $E$ ,  
 $\Omega^k(M, E)$   
 consists of maps

$$\omega: \underbrace{\{X(M) \times \dots \times X(M)\}}_k \rightarrow \Gamma(E)$$

- which are
- Skew symmetric
  - $C^\infty(M)$ -linear in each argument

Or:  $\Omega^k(M, E) = \Gamma(\underbrace{\wedge^k T^*M \otimes E}_{\text{"}})$

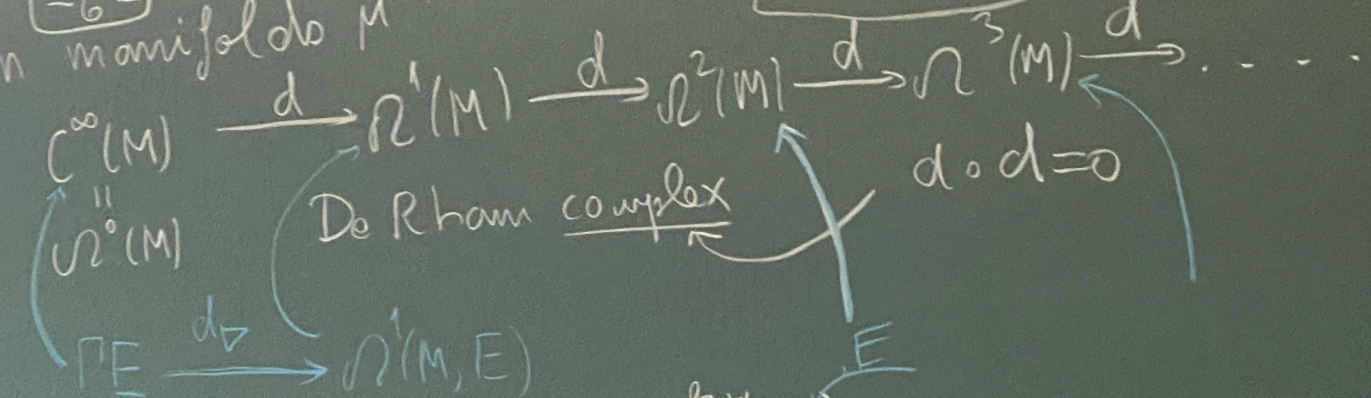
$\text{Alt}^k(T_x M, E_x) = \text{the vector bundle } / M \text{ whose fiber above } x \in M$   
 $\text{Alt}^k(T_x M, E_x) = \left\{ \omega_x: \underbrace{T_x M \times \dots \times T_x M}_k \rightarrow E_x \mid \begin{array}{l} \text{multilin} \\ \text{skew symm} \end{array} \right\}$



$x(s)$   
 $x'(s)$

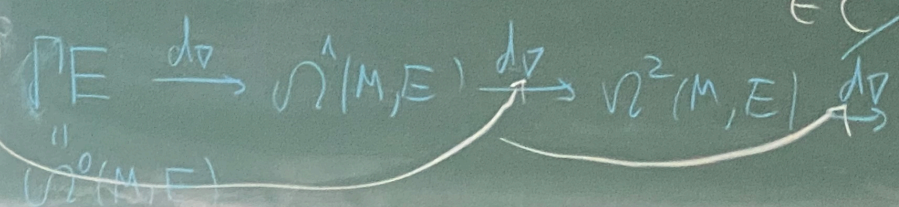
On  $(-G)$  manifold  $M$

$$\omega \in \Omega^k(M) : \underbrace{\omega : \underbrace{T(M) \times \dots \times T(M)}_k \rightarrow C^\infty(M)}$$



Def: Give  $\nabla$  define

$$\nabla_{X_i} \omega(X_0, \dots, X_k) = \sum_{l=0}^k (-1)^i \underbrace{\left( \frac{\partial}{\partial X_i} \omega(X_0, \dots, X_{i-1}, X_l, X_{i+1}, \dots, X_k) \right)}_{\in C^\infty(M) \quad \Gamma(E)} + \sum_{0 \leq i < j \leq k} (-1)^{i+j} \underbrace{\omega([X_i, X_j], X_0, \dots, \hat{X}_i, \dots, \hat{X}_j, \dots, X_k)}_{\in C^\infty(M) \quad \Gamma(E)}$$



Corollary  
a contr

$$H_t = H(-, t) : M \rightarrow \dots$$

$$H_0 \sim H_1$$

Do it to

Rk

Def: Given  $\Gamma$  a path  $\gamma : I \rightarrow E$



$\Omega^k(M, E)$  consists of  $C^\infty(M)$ -multilinear, skew-symmetric maps

$$\omega : \underbrace{\mathcal{X}(M) \times \dots \times \mathcal{X}(M)}_k \rightarrow PE$$

$$E_1 \times E_2 \rightarrow E$$

Classical wedge operations:

$$\left\{ \begin{array}{l} \Omega^k(M) \times \Omega^l(M) \rightarrow \Omega^{k+l}(M) \\ (\omega, \eta) \longmapsto \omega \wedge \eta \end{array} \right. \text{ where } (\omega \wedge \eta)(X_1, \dots, X_{k+l}) =$$

$$= \sum_{\sigma \in S_{k+l}} \text{sgn}(\sigma) \omega(X_{\sigma(1)}, \dots, X_{\sigma(k)}) \eta(X_{\sigma(k+1)}, \dots, X_{\sigma(k+l)})$$

Variations:

$$\left\{ \begin{array}{l} \Omega^k(M) \times \Omega^l(M, E) \rightarrow \Omega^{k+l}(M, E) \\ \Omega^k(M, E) \times \Omega^l(M) \rightarrow \Omega^{k+l}(M, E) \\ \textcircled{\Omega^k(M, \text{End}(E)) \times \Omega^l(M, E) \rightarrow \Omega^{k+l}(M, E)} \end{array} \right.$$

$\text{Hom}(E, E)$

Cool: (A)  $\mathbb{P}(B) \Rightarrow$  can use  $K_0$  to get:

$$\left\{ \begin{array}{l} \Omega^l(M, E) \rightarrow \Omega^{l+2}(M, E) \\ \omega \longmapsto K_0 \wedge \omega \end{array} \right.$$

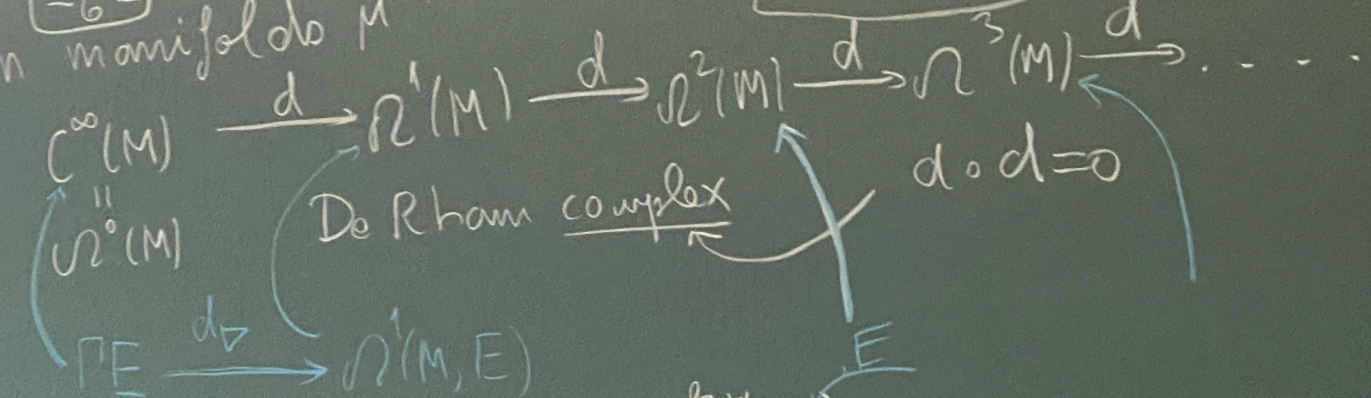
... this is  $d_D$  !!



$x(s)$   
 $x'(s)$

On  $(-G)$  manifold  $M$

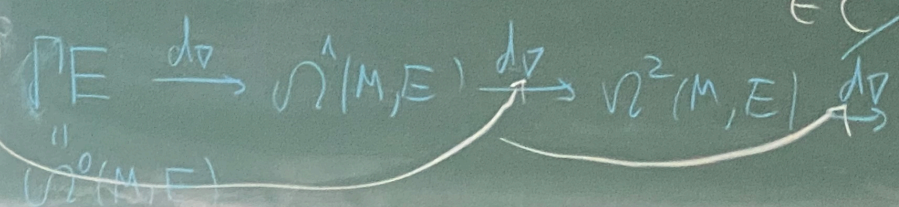
$$\omega \in \Omega^k(M) : \omega = \underbrace{x(M) \times x'(M)}_k \rightarrow C^\infty(M)$$



Def: Give  $\nabla$  define

$$\nabla_{X_i} \omega(X_0, \dots, X_k) = \sum_{l=0}^k (-1)^i \underbrace{\left( \frac{\partial}{\partial X_i} \omega(X_0, \dots, X_{i-1}, X_l, X_{i+1}, \dots, X_k) \right)}_{\in C^\infty(M) \quad \Gamma(E)}$$

$$+ \sum_{0 \leq i < j \leq k} (-1)^{i+j} \underbrace{\omega([X_i, X_j], X_0, \dots, \hat{X}_i, \dots, \hat{X}_j, \dots, X_k)}_{\in C^\infty(M) \quad \Gamma(E)}$$



Corollary  
a contr

$$H_t = H(-, t) : M \rightarrow \dots$$

$$H_0 \sim H_1$$

Do it to

Rk

Def: Given  $\gamma$  a path  $\gamma : I \rightarrow E$



$$\mathbb{R}E \xrightarrow{d\sigma} \Omega^1(M, E) \xrightarrow{d\sigma} \Omega^2(M, E) \xrightarrow{d\sigma} \dots$$

- 8 -

Def: Given  $\nabla$ , the curvature of  $\nabla$  is

$$K_{\nabla} : \mathcal{X}(M) \times \mathcal{X}(M) \times \mathbb{R}E \rightarrow \mathbb{R}E$$

$$(X, Y, s) \mapsto K_{\nabla}(X, Y)(s) =$$

$$= \nabla_X(\nabla_Y(s)) - \nabla_Y(\nabla_X(s)) - \nabla_{[X, Y]}(s)$$

Call  $\nabla$  flat  
if  $K_{\nabla} = 0$ .

Remember:  $L_{[X, Y]}(f) = L_X(L_Y(f)) - L_Y(L_X(f))$

Interesting:  $C^{\infty}(M)$ -linear in  $X, Y$  &  $s$

$$K_{\nabla} : \mathcal{X}(M) \times \mathcal{X}(M) \xrightarrow{\sigma} \Gamma(\text{End } E)$$

$$(X, Y) \mapsto K_{\nabla}(X, Y) : \mathbb{R}E \rightarrow \mathbb{R}E$$

$C^{\infty}(M)$ -lin in  $s$

$$K_{\nabla} \in \Omega^2(M, \text{End } E) \quad (A)$$

Def Th  
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Proposit

linear

$\mathbb{R} : \text{Li}$

er U.  $\{2\}$   
 $\in M_r(\mathbb{R}^n)$   
 $(f \in C^{\infty}(U))$   
over U

$\mu(t) \in E_{\sigma(t)}$   
"path above  $\sigma$ "  
ve the same  $\sigma$

$I \rightarrow \mathbb{R} \Rightarrow$   
 $\sigma(t) \omega_j(\sigma(t)) e_j(\sigma(t))$

wi  
T  
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$\Omega^k(M, E)$  consists of  $C^\infty(M)$ -multilinear, skew-symmetric maps

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$$E_1 \times E_2 \rightarrow E$$

Classical wedge operations:

$$\left\{ \begin{array}{l} \Omega^k(M) \times \Omega^l(M) \rightarrow \Omega^{k+l}(M) \\ (\omega, \eta) \longmapsto \omega \wedge \eta \end{array} \right\} \text{ where } (\omega \wedge \eta)(X_1, \dots, X_{k+l}) =$$

$$= \sum_{\sigma \in S_{k+l}} \text{sgn}(\sigma) \omega(X_{\sigma(1)}, \dots, X_{\sigma(k)}) \eta(X_{\sigma(k+1)}, \dots, X_{\sigma(k+l)})$$

Variations:

$$\left\{ \begin{array}{l} \Omega^k(M) \times \Omega^l(M, E) \rightarrow \Omega^{k+l}(M, E) \\ \Omega^k(M, E) \times \Omega^l(M) \rightarrow \Omega^{k+l}(M, E) \\ \textcircled{\Omega^k(M, \text{End}(E)) \times \Omega^l(M, E) \rightarrow \Omega^{k+l}(M, E)} \end{array} \right.$$

$\text{Hom}(E, E)$

Cool: (A)  $\mathbb{P}(B) \Rightarrow$  can use  $K_0$  to get:

$$\left\{ \begin{array}{l} \Omega^l(M, E) \rightarrow \Omega^{l+2}(M, E) \\ \omega \longmapsto K_0 \wedge \omega \end{array} \right.$$

... this is  $d_D$ !!