

Scratch paper:

$$\lambda: U \rightarrow \Omega \subseteq \mathbb{R}^m$$

$$X|_U \in \mathfrak{X}(U)$$

$$\lambda_* (X|_U) \in \mathfrak{X}(\Omega)$$

$$\lambda_* (X|_U) = \sum F_i^x \frac{\partial}{\partial x_i}$$

$$F_i^x \in C^\infty(\Omega)$$

$F: M \rightarrow N$ diffeom induces

$$F_*: \mathfrak{X}(M) \rightarrow \mathfrak{X}(N)$$

$$\begin{matrix} \psi \\ X \\ (X_p \in T_p M \\ p \in M) \end{matrix}$$

$$\psi?$$

$$F_*(X)$$

for $g \in N$,
 $p = F^{-1}(g)$

$$F_*(X)_g = \left(dF_p \left(X_p \right) \right)_g$$

$$\underbrace{\quad}_{T_p M}$$

$$\underbrace{\quad}_{T_p N}$$

$$\underbrace{\quad}_{T_g N}$$

Operations:

• ADDITION $\cdot (X+Y)_p$

• MULTIPLICATION BY SCALAR

• " " " " " "

ie operation $C^\infty(M) \times \mathfrak{X}(M)$

• actions of $X \in \mathfrak{X}(M)$ by

• LIE BRACKET of vectors $\mathfrak{X}(M) \times \mathfrak{X}(M)$

→ skew symmetric $[X, Y] = -[Y, X]$

→ be linear $[X_1 + X_2, Y] = [X_1, Y] + [X_2, Y]$

→ Jacobi $[X, Y], Z = [X, [Y, Z]] + [Y, [X, Z]] + [Z, [X, Y]] = 0$

Extra (all together): $[X, fY] = [X, Y] + X(f)$

$$L_{[X, Y]} = \underbrace{d_X \circ d_Y - d_Y \circ d_X}$$

All we know about $[\cdot, \cdot]$ is its definition.

$$L_{[X, Y]}(f) = d_X(d_Y(f)) - d_Y(d_X(f)) \quad \forall f \in C^\infty(M)$$

Proof of Jacobi: The LHS is a vector field (call it V). To show $V=0$ to show that $d_V = 0$: Look at $d_V(f) = d_{[X, Y]}(f) + \dots$

$$\begin{aligned} &= d_{[X, Y]}(d_Z(f)) - d_Z(d_{[X, Y]}(f)) + \dots \\ &= d_X d_Y d_Z(f) - d_Y d_X d_Z(f) - d_Z(d_X d_Y(f)) + \dots \end{aligned}$$

- 1 -

Reminder :

- vector spaces $T_p M$ & differentials $(dF)_p: T_p M \rightarrow T_{F(p)} N$
- $\frac{d\gamma}{dt}(t) \in T_{\gamma(t)} M$ for any curve $\gamma: I \rightarrow M$ $\frac{d}{dt}(s) = \gamma(s+t)$
 $\frac{d\gamma}{ds}(0)$
- basis $\left(\frac{\partial}{\partial x_1}\right)_p, \dots, \left(\frac{\partial}{\partial x_m}\right)_p$ of $T_p M$ (\forall) chart (U, χ) & $p \in U$.
- vector field X on M : $M \ni p \mapsto X_p \in T_p M$, "smooth"

\rightarrow locally : (\forall) chart $\chi: U \rightarrow \Omega$, writing

$$X_p = \sum_{i=1}^m \underbrace{F_i^X(\chi(p))}_{\mathbb{R}^m} \left(\frac{\partial}{\partial x_i}\right)_p, \text{ the functions } F_i^X: \Omega \rightarrow \mathbb{R} \text{ are smooth}$$

\rightarrow globally : X induces \mathcal{L}_X that lands in $C^\infty(M)$:

$$\mathcal{L}_X: C^\infty(M) \rightarrow C^\infty(M), \quad \mathcal{L}_X(f)(p) = \partial_{X_p}(f) = (df)_p(X_p)$$

Operations:

-2-

$\mathfrak{X}(M) \subset \mathfrak{X}(M)$

• ADDITION: $(X+Y)_p = X_p + Y_p$

• MULTIPLICATION BY SCALARS: $(\lambda \cdot X)_p = \lambda \cdot X_p$

• SMOOTH FUNCTIONS: $(f \cdot X)_p = f(p)X_p$
 i.e. Operation $C^\infty(M) \times \mathfrak{X}(M) \rightarrow \mathfrak{X}(M), (f, X) \mapsto fX$

(1) a vector space
 (2) a $C^\infty(M)$ -module

• actions of $X \in \mathfrak{X}(M)$ by DERIVATIONS $d_X: C^\infty(M) \rightarrow C^\infty(M)$

$d_X(fg) = f d_X(g) + g d_X(f)$

• LIE BRACKET of vector fields
 $\mathfrak{X}(M) \times \mathfrak{X}(M) \rightarrow \mathfrak{X}(M), (X, Y) \mapsto [X, Y]$

(3) $\mathfrak{X}(M)$ is a Lie algebra

- skew symmetric: $[Y, X] = -[X, Y]$
- bilinear: $[X_1 + X_2, Y] = [X_1, Y] + [X_2, Y]$ etc
- Jacobi: $[X, Y], Z] + [[Y, Z], X] + [[Z, X], Y] = 0$

Extra (all together): $[X, fY] = f[X, Y] + d_X(f)Y$

for $g \in N$
 $p = F^{-1}(g)$
 $dF_p(X_p)$
 $T_p M$
 $T_{F(p)} N$
 $T_g N$

show $V=0$

+ ...

Sketch paper: $\lambda: U \rightarrow \Omega \subset \mathbb{R}^m$

$$X|_U \in \mathfrak{X}(U)$$

$$X_* (X|_U) \in \mathfrak{X}(\Omega)$$

$$X_* (X|_U) = \sum F_i^x \frac{\partial}{\partial x_i}$$

$$F_i^x \in C^\infty(\Omega)$$

$$d_{[X,Y]} = d_X \circ d_Y - d_Y \circ d_X$$

All we know about $[,]$ is its definition:

$$d_{[X,Y]}(f) = d_X(\alpha_Y(f)) - d_Y(\alpha_X(f)) \quad (\forall f \in C^\infty(M))$$

proof of Jacobi: The LHS is a vector field. Call it V . To show $V=0$ look at $d_V(f) = d_{[X,Y]}(f) + \dots$

$$\Rightarrow \text{to show that } d_V = 0: \text{ Look at } d_V(f) = d_{[X,Y]}(f) + \dots = d_X d_Y d_Z(f) - d_Y d_X d_Z(f) - d_Z d_X d_Y(f) + \dots$$

Ex: on \mathbb{R}^m : $\left[\frac{\partial}{\partial x_i}, \frac{\partial}{\partial x_j} \right] = 0$

For arbitrary v. fields on \mathbb{R}^m

$$\sum F_i \frac{\partial}{\partial x_i}$$

use bilinearity and the HW.

Ex: $\left[\frac{\partial}{\partial x}, xy \frac{\partial}{\partial x} + e^{x+2y} \frac{\partial}{\partial y} \right] =$

$$= \left[\frac{\partial}{\partial x}, xy \frac{\partial}{\partial x} \right] + \left[\frac{\partial}{\partial x}, e^{x+2y} \frac{\partial}{\partial y} \right] =$$

$$= xy \left[\frac{\partial}{\partial x}, \frac{\partial}{\partial x} \right] + d \left(\frac{\partial}{\partial x} \right) \left(\frac{\partial}{\partial y} \right) + \dots$$

$$= y \frac{\partial}{\partial x} + e^{x+2y} \frac{\partial}{\partial y}$$

Operations:

- ADDITION - $(X+Y)$
- MULTIPLICATION
- " " " " " "
- i.e. operation
- actions of X
- LIE BRACKET

- skew sym
- be linear
- Jacobi

Extra (all together) $\dots = 0$

→ globally: X induces \mathcal{L}_X that lands in $C^\infty(M)$ are smooth

$$\mathcal{L}_X: C^\infty(M) \rightarrow C^\infty(M), \quad \mathcal{L}_X(f)(p) = \partial_{X_p}(f) = (df)_p(X_p)$$

Exercise

-5-

DEF: Given $X \in \mathfrak{X}(M)$, an integral curve of X is any $\gamma: I \rightarrow M$ smooth (with $I \subseteq \mathbb{R}$ open interval, ~~$\partial \in I$~~)

s.t.
$$\frac{d\gamma}{dt}(t) = X_{\gamma(t)} \quad (\forall) t \in I$$

Say that γ starts at $p \in M$ if $0 \in I$, $\gamma(0) = p$.

-6-

Ex: $M = \mathbb{R}^2$, $X = \frac{\partial}{\partial x} + \lambda \frac{\partial}{\partial y} \in \mathfrak{X}(\mathbb{R}^2)$, $\lambda \in \mathbb{R}$ constant

Integral curve: $\gamma(t) = (x(t), y(t))$

$$\frac{d\gamma}{dt}(t) = X_{\gamma(t)}$$

$$\dot{x}(t) \cdot \left(\frac{\partial}{\partial x}\right)_{\gamma(t)} + \dot{y}(t) \cdot \left(\frac{\partial}{\partial y}\right)_{\gamma(t)} = \left(\frac{\partial}{\partial x}\right)_{\gamma(t)} + \lambda \left(\frac{\partial}{\partial y}\right)_{\gamma(t)}$$

$$\begin{cases} \dot{x}(t) = 1 \\ \dot{y}(t) = \lambda \end{cases}$$

$$\Rightarrow \begin{cases} x(t) = t + a \\ y(t) = \lambda t + b \end{cases} \Rightarrow \gamma_{a,b} \text{ one for each } a, b \in \mathbb{R}$$

$$\gamma_{a,b}(t) = (t+a, \lambda t+b)$$

Rk 1: Prescribing $\gamma(0) = (a, b) \Rightarrow$ precisely one integral curve

Rk 2: We can use $I = \mathbb{R}$, i.e. $\gamma_{a,b}$ makes sense as $\mathbb{R} \rightarrow \mathbb{R}^2$.

Exercise: $y \frac{\partial}{\partial x} - x \frac{\partial}{\partial y} \in \mathfrak{X}(\mathbb{R}^2)$

$$M = \mathbb{R}^2, \quad X = \begin{pmatrix} -x^2 \\ -y \end{pmatrix} \frac{\partial}{\partial x} - y \frac{\partial}{\partial y}$$

$$\begin{cases} \dot{x}(t) = -x^2(t) \\ \dot{y}(t) = -y(t) \end{cases} \Rightarrow \dots \Rightarrow \varphi_{a,b}(t) = \begin{pmatrix} \frac{a}{at+1} \\ be^{-t} \end{pmatrix}$$

$$\gamma(t) = (\underbrace{x(t)}_{\text{circled}}, \underbrace{y(t)}_{\text{circled}})$$

Rk1: ✓

Rk2: Makes sense on the entire $I = \mathbb{R}$ only when $a=0$.

For $a < 0$ one could use $(-\infty, -\frac{1}{a})$ or $(-\frac{1}{a}, \infty)$.

$$y + a^2 = e^{-tb} \quad \frac{d}{dt} \ln|y + a^2| = -b$$

$$y(t) = e^{-tb} \quad \frac{y'}{y + a^2} = -1$$

ER More generally, in any $\Omega \subseteq \mathbb{R}^m$ open:

$X \in \mathcal{X}(\Omega)$: $X = \sum_{i=1}^m F^i \frac{\partial}{\partial x_i}$] \rightarrow

curve γ : $\gamma = (\gamma^1, \dots, \gamma^m)$

to solve: $\frac{d\gamma^i}{dt}(t) = F^i(\gamma^1(t), \dots, \gamma^m(t))$

Initial conditions: $\gamma^1(0) = a, \gamma^2(0) = b, \dots$

GIVEN: F

TO SOLVE

THM:

and an
coincide

s.t.,

GIVEN $F = (F_1, \dots, F_m): \Omega \rightarrow \mathbb{R}^m$ smooth,

$$\frac{dx}{dt}(t) = F(x(t)), \quad x(0) = x_0 \quad (*)$$

given

Cauchy local $\exists!$

THM: $(\forall) x \in \Omega$, $(*)$ has a solution $x: I \rightarrow \Omega$

any two solutions $x_1: I_1 \rightarrow \Omega$, $x_2: I_2 \rightarrow \Omega$
coincide on some open $J \subseteq I_1 \cap I_2$

Moreover, $\left\{ \begin{array}{l} \text{sol. of } (*) \text{ depend smoothly on } x_0 \\ \text{for } (\forall) x_0 \in \Omega \end{array} \right.$

$\exists \mathcal{V}_{x_0} \subseteq \Omega$ open, $\exists \varepsilon > 0$,
 $\exists \phi: \mathcal{V}_{x_0} \times (-\varepsilon, \varepsilon) \rightarrow \Omega$ smooth

st. $(\forall) x \in \mathcal{V}_{x_0}$

Reminder:

• vector spaces $T_p M$ & differentials $(dF)_p: T_p M \rightarrow T_{F(p)} N$

Ex: $M = \mathbb{R}^n$
Integral curve

-10-

DEF: Given $X \in \mathfrak{X}(M)$, an integral curve of X is any $\gamma: I \rightarrow M$ smooth (with $I \subseteq \mathbb{R}$ open interval, ~~\mathbb{R}~~) s.t.

$$\frac{d\gamma}{dt}(t) = X_{\gamma(t)} \quad (\forall t \in I)$$

Say that γ starts at $p \in M$ if $0 \in I, \gamma(0) = p$.

Prop: Given $X \in \mathfrak{X}(M)$:

- $(\forall) p \in M, \exists$ int. curve $\gamma: I \rightarrow M$ of X s.t. $\gamma(0) = p$
- any two integral curves γ_1 and γ_2 of X which coincide at some t_0 , must coincide on a $(t_0 - \epsilon, t_0 + \epsilon)$ for $\epsilon > 0$.

Corollary: Given $X \in \mathfrak{X}(M), (\forall) p \in M \exists!$ $\gamma_p^X: I_p^X \rightarrow M$ maximal integral curve of X starting at p .

X is called complete if $I_p^X = \mathbb{R} \quad (\forall) p \in M$

(\exists) integral curve $\tilde{\gamma}: \tilde{I} \rightarrow M$ s.t. $\tilde{I} \supsetneq I, \tilde{\gamma}|_I = \gamma$

pf:

the prop
I just
For the

integro

pf: $A \neq \emptyset$

$A \neq \emptyset$

To prove:

Corollary:

$\frac{dx}{dt}(t) = X_x(t)$ It suffices to work in a chart χ
 $\chi(0) = p$

$$\chi_*(X) = \sum F_i^x \frac{\partial}{\partial x_i} \quad x \in \mathcal{D}$$

the problem, transferred to $\mathcal{D} \subseteq \mathbb{R}^m$ is the one that I just erased ☹️ Just apply classical Cauchy $\exists!$!

For the corollary: Remark: if $\gamma_1: I_1 \rightarrow M, \gamma_2: I_2 \rightarrow M$ integral curves, $\exists t_0 \in I_1 \cap I_2$ s.t. $\gamma_1(t_0) = \gamma_2(t_0) \Rightarrow \gamma_1 = \gamma_2$ on $I_1 \cap I_2$.

e) Pr: $A = \{t \in I_1 \cap I_2 : \gamma_1(t) = \gamma_2(t)\} \subseteq I_1 \cap I_2$ (interval)
 $\emptyset \neq A$
 $A \neq \emptyset$

To prove: $A = I_1 \cap I_2$.
Corollary: just put together the int. curves that we know to exist locally

Given $F = (F_1, \dots, F_m)$

Cauchy local $\exists!$!

THM: $(\forall) x \in \mathcal{D},$

Moreover $\{ \text{sol. of } (1) \}$

> precisely one integral curve

$\gamma_{a,b}$ makes sense as $\mathbb{R} \rightarrow \mathbb{R}^2$

$p = (a, b)$

$I_p = \mathbb{R}$

$\gamma_p: I_p \rightarrow \mathbb{R}^2, \gamma_p(t) = (t+a, t+b)$

[12]

Ex: $p = (a, b), I_p = \begin{cases} \mathbb{R} \\ (-\infty, -\frac{1}{a}] \\ [-\frac{1}{a}, \infty) \end{cases}$
 $\gamma_p =$ the maximal IC, on I_p

$y + \frac{1}{y} = 0$
 $y(t) = \dots$
 $a = \dots$
 $a < \dots$
 $a > \dots$

to work in a chart χ

$\chi_*(X) = \sum F_i^x \frac{\partial}{\partial x_i}$

\mathbb{R}^m is the one that apply classical Cauchy $\exists!$

$\gamma_1: I_1 \rightarrow M, \gamma_2: I_2 \rightarrow M$
 $I_1 \cap I_2 \neq \emptyset \Rightarrow \gamma_1 = \gamma_2$ on $I_1 \cap I_2$
 part 2 of \mathbb{R}

[9]

GIVEN $F = (F_1, \dots, F_m): \Omega \rightarrow \mathbb{R}^m$ smooth

$\frac{dx}{dt}(t) = F(x(t)), \gamma^*$

Cauchy local $\exists!$

THM: $(\forall) x \in \Omega, (*)$ has a solution $\gamma: I \rightarrow M$
 any two solutions γ_1, γ_2 coincide on some open

Moreover, sol. of $(*)$ depend smoothly on x_0
 $(\forall) x_0 \in \Omega \exists \phi: \mathcal{D}_{x_0} \rightarrow \mathcal{D}_{x_0}$



M

43-

X is called complete if

$= \emptyset$

$$I_p^X = \mathbb{R} \iff \emptyset \in M$$

A

To

Corollary