

An example Contribution for CG:YRF 2014

Anton Example*

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Abstract

This example contribution builds on previous work [2], but makes several significant improvements. We removed the silly logo, and instead added a much more impressive picture showcasing some very Fancy Geometry. Also, there are more theorems.

1 Introduction

Well, the usual ...

Theorem 1 *We start with this theorem.*

Conjecture 1 *Could it really be like this?*

Observation 1 *Probably not ...*

Definition 1 *Some things are just not definable ..*

We also have a figure!

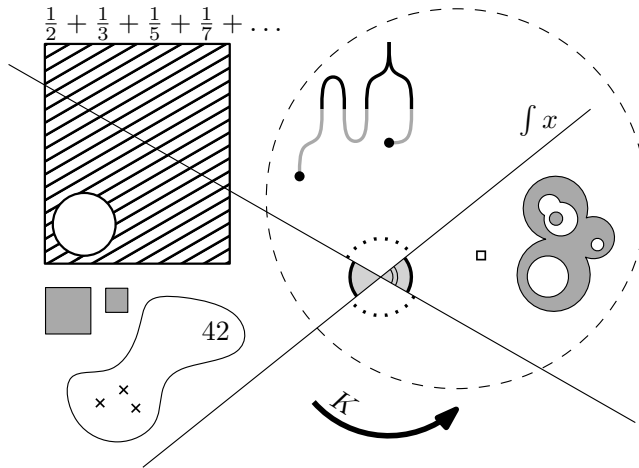


Figure 1: Fancy Geometry.

Theorem 2 *This is the most important theorem.*

Proof. It even comes with a proof ... \square

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Lemma 3 *And then we also found this lemma ...*

There should be some more text explaining research results in some additional sections, but since this is only an example file ...

Theorem 4 *... we would like to finish with another theorem.*

2 Conclusion

What we did is amazing and improves everything that was there before.

References

- [1] P. K. Agarwal, J. Basch, L. J. Guibas, J. Hersberger, and L. Zhang. Deformable free space tilings for kinetic collision detection. In *Proc. 5th Workshop Algorithmic Found. Robotics*, pages 83–96. A. K. Peters, 2001.
- [2] A. Example and S. Veryknown. An example Contribution for CG:YRF 2013. In *Abstracts. 2nd Computational Geometry Young Researchers Forum*, pages 1–1, 2013.